



# Design, construction and results in UST\_1 , a small low-cost educational stellarator

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# Outline

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I) Background data

II) **UST\_1** : Coils, vacuum vessel, mechaniser, vacuum and control system

III) **SimPIMF** code and **Optimization** of coils

IV) **Experimental results** : Field mapping system and magnetic surfaces

V) **Chronological description** : Evolution, alternatives, difficulties and solutions

# Background data

## UST\_1 basic features

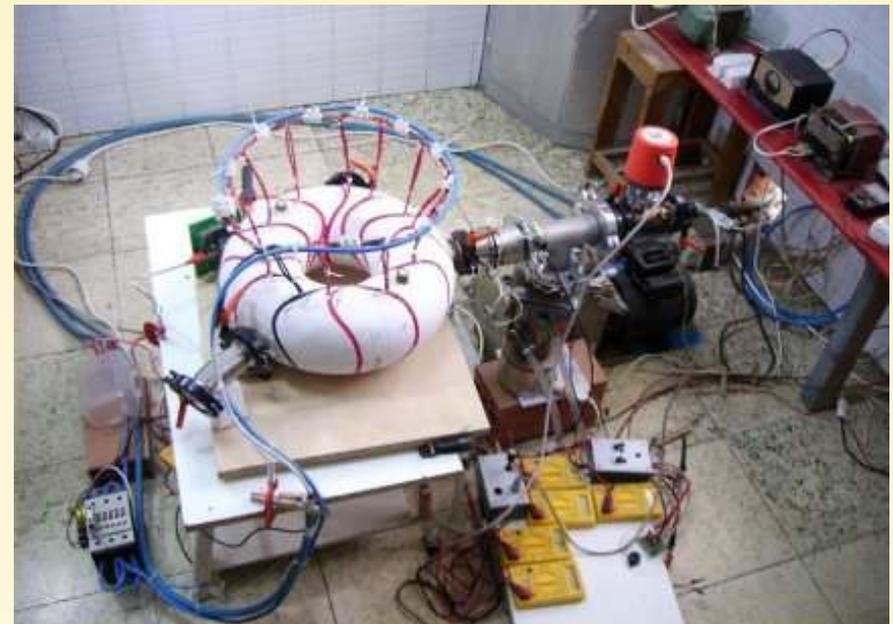
- UST\_1 is a low cost small educational stellarator built in a personal laboratory
- Modular coils,  $R = 125\text{mm}$  ,  $\langle a \rangle = 21\text{ mm}$  ,  $A_p = 6$  , 2 field periods ,  $V_p = 1.1L$
- **$B_0 = 40\text{mT}$**  , presently (designed for  $\sim 0.1\text{T}$ )
- **Pulse length** : 2 s at  $B_0 = 40\text{mT}$
- **Heating** : ECH :  $0.8\text{kW}$  at  $2.45\text{GHz}$  . Being developed.
- **Diagnostics** : e-beam field mapping. (RGA and visible spectroscopy)\*
- **Vacuum system** : Best  $5\text{mPa}$  . Mechanical, diffusion pump, gauges

## The cost and the quality

- Objective : Minimum cost
- Quality & precision : medium, but creativity and effort for maximum rate quality/cost

## Motivation to built UST\_1

- Learn, experiment with fusion technologies and support to my offer in fusion research



## *Section II*

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**Section II . UST\_1** : Coils,  
vacuum vessel, mechaniser, vacuum  
and control system, calculated  
features

## Coils and coil structure

Type & Periods	Modular coils ; m=2
Winding surface	Circular pol. & tor. R = 119mm r=57mm
Number of coils	12 (3 different shapes)
Turns per coil	6
Conductor	flexible, special copper 6mm <sup>2</sup>
Winding pack structure	1 double pancake per coil, 3 layers
Winding pack size	7mm width x 10.5 mm depth
Case	Compact plaster frame
Parameters of shape	1.45 ; 1.3 ; 1.55 ; 0.65
Current, present (ECH 2 <sup>nd</sup> )	335 A , 2 kA-turn
Current, planned (ECH 1 <sup>st</sup> )	687 A , 4.1 kA-turn
Power supplies, present	5 batteries DC 12V, ~17Kw supplied to coils



The 12 modular coils  
finished. (Before installation in  
the system)

# Selection of suitable conductor

## Constraints :

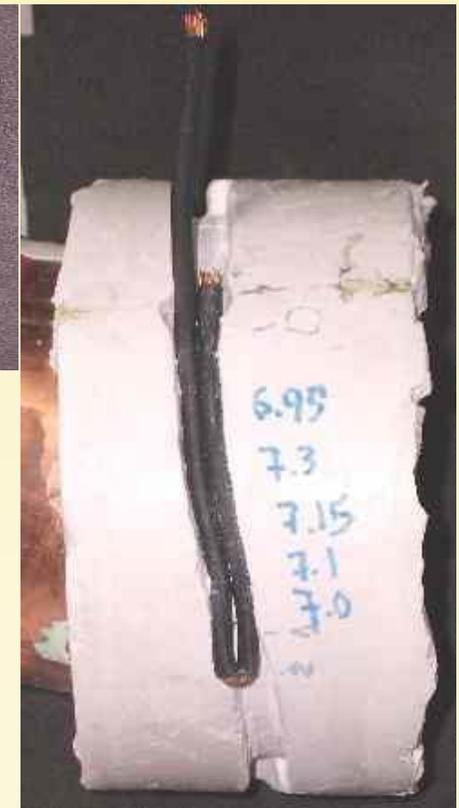
- Relatively **large section** and **few turns** to allow low voltage battery operation
- **Maximum ratio copper/total section**
- **Narrow winding pack** to allow a single pass mechanization of the groove
- The **plaster strength is low** and rigid copper conductor was not adequate

## Alternatives:

Several test



**Selection :** ►  
6mm<sup>2</sup> flexible  
cond., unsleeved  
and shrinkable  
sleeved. Diam.  
ext =3.5mm

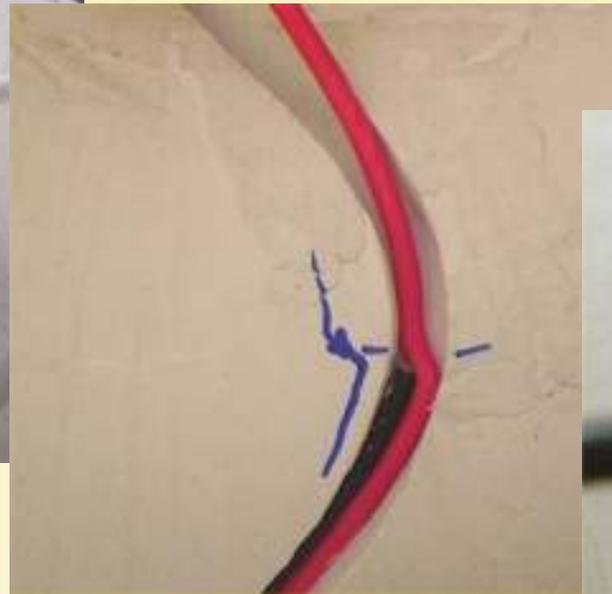


Test of groove-coil

## Winding process of coils



◀ Grooves mechanised in the compact frame ,  
7mm width, 12.5mm depth



Internal crossover and  
auxiliary winding coil  
(black conductor)



Compacting and locating  
conductors in the groove



Detail of the device to  
mechanise modular coils

# Vacuum vessel



Gutter copper elbow.  
0.8mm wall thickness



◀ Vacuum vessel formed by 5 elbows of 75°

Tube 80mm diam. R-torus 119mm. Low T silver soldered



Detail of hole for port and two rings to reinforce the VV

Finished VV under leak test. 3 ports of 35mm diam. and NW40, high T silver brazed. One glass window. No ferromagnetic materials.



# Coil Support structure

## Constraint : Low cost

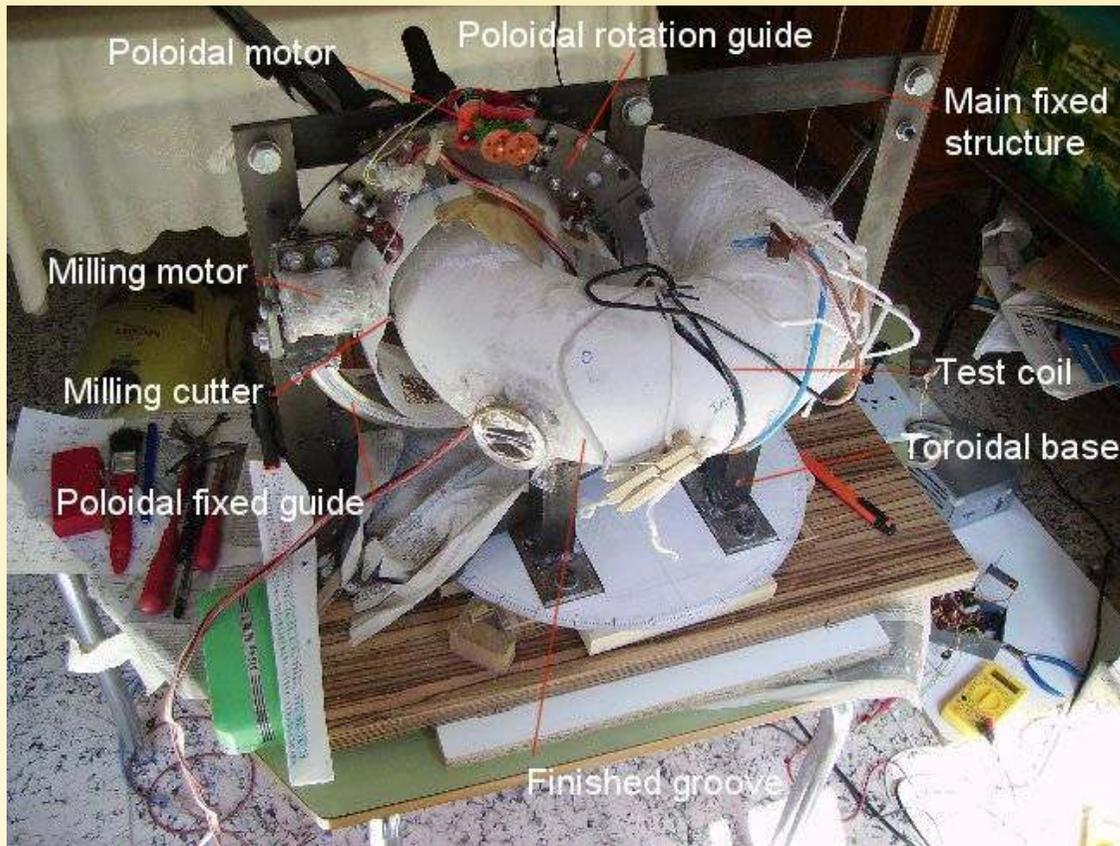
**Alternatives** were studied to obtain notable accuracy at low cost :

- Coils style HSX or W7-X : Expensive to wind, locate, regulate and measure
- Style CTH : Very high cost of min. 6 pieces CNC mechanised, difficult to locate and measure.
- Internal, like in CNT or QPS. Issues : Vacuum tightness, wind & locate
- Frames style QPS : How to fabricate the frames?, many fasteners to fix the coils, assembling, measurement.
- Structural only one turn : Perturbations of magnetic field due to ends. How to conform the turn?
- Fasteners on toroidal surface located with **measuring device**: Low accuracy

**Solution (patented)** : Innovative mechanising device. A **special milling machine** working in toroidal coordinates that acts as:

- *measuring device.*
- *mechanising device for grooves*
- *instrument to “locate” the coils*
- *auxiliary apparatus to create toroidal moulds*

## Device to mechanise modular coils



- **It was devised, designed, patented, built, tested** and grooves manufactured
- It took long time and effort, but successful result

### Advantages :

- Mechanization and positioning of coils is the same process → reduced field errors ( $<0.2^\circ$  toroidal,  $<0.1^\circ$  verticality in UST\_1).
- Errors are similar to CNC deviations, so very small.
- Different prove of principle can be easily built.
- At least four different functions.
- Able for non-circular surfaces.

### Drawbacks :

- No suitable for big devices?
- No adequate for highly shaped and compact devices.
- Needs special cutter if wide grooves.

## Device to mechanise modular coils



### Some elements :

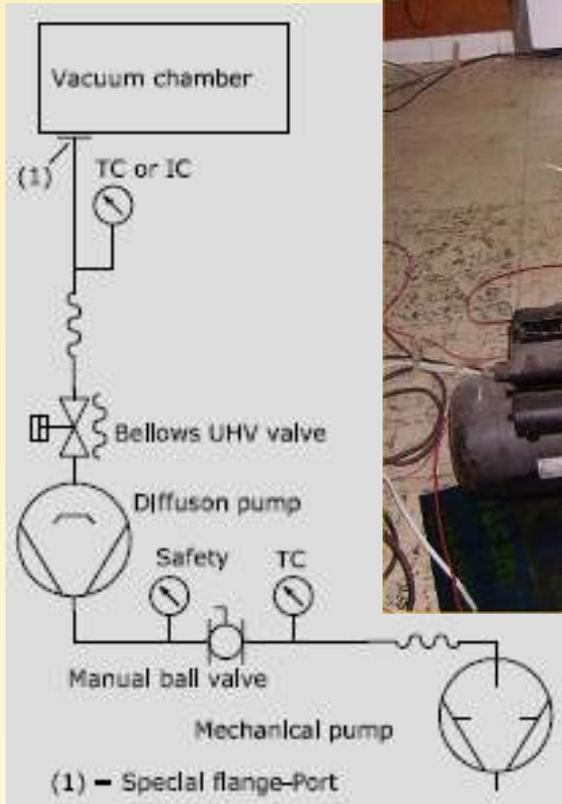
- Poloidal guide + motor
  - Milling motor and milling cutter
  - Support porch
  - Fixed two halves of ring
  - Powder sucking tube
  - Powder poloidal cover
  - List of coordinates
- 
- Some mechanised grooves
  - One test coil (black)



It takes ~2 hours to mechanise a groove 7mm width, 12.5mm depth. Poloidal forward speed adjustable according to slope. Manual (by now) toroidal position

**Auxiliary function** : Cut toroidal moulds.  
Support, hot semicircular wire and mould ►

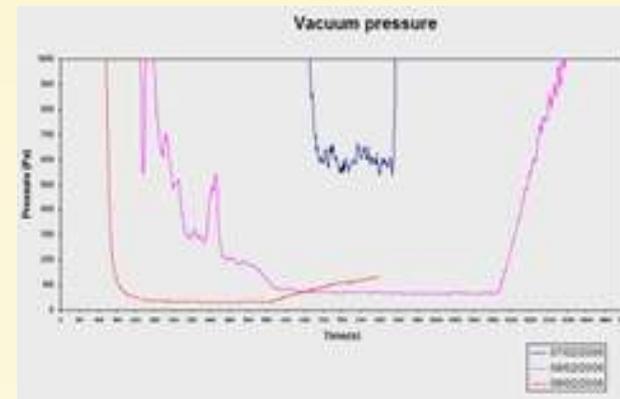
# Vacuum system



## Main elements

- Pfeiffer DUO 004A mechanical pump , 4m<sup>3</sup>/h
- Leybold diffusion pump ~150L/s (DC-704 oil)
- Edwards AIMS = Active inverted magnetron gauge , 1Pa - 10<sup>-6</sup> Pa
- Lesker Thermocouple gauges x 2: 100 Pa – 0.1Pa
- Capacitance gauge : 5 Torr - ~ 10Pa
- Bourdon manometer
- NW50 fittings for high vacuum,

Vacuum system layout  
(The Varian UHV valve was recently removed to increase conductance)

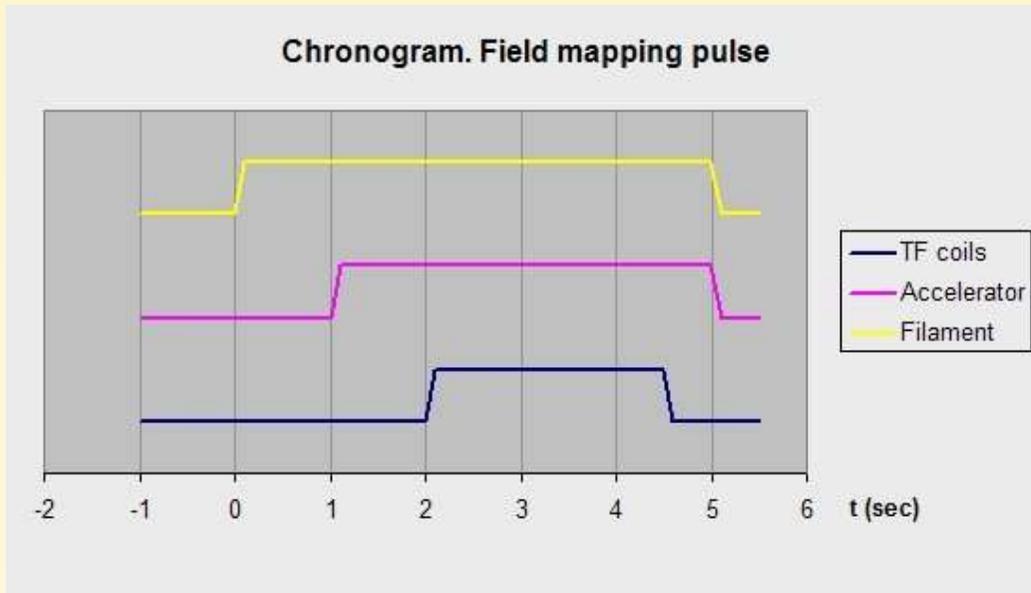


Achieved  
5mPa

Outgassing  
improvement  
with time

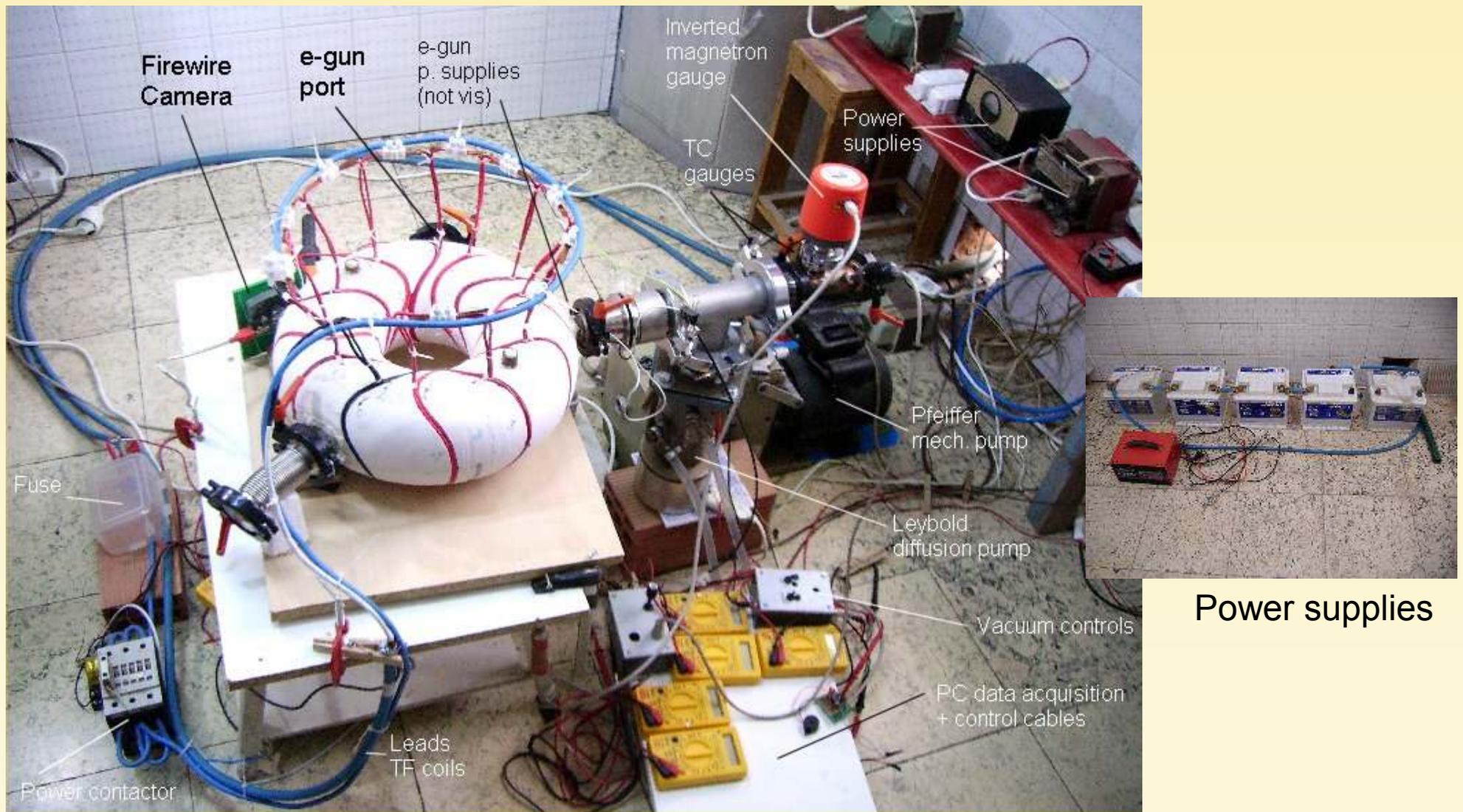
- 2 x PC and short “C” code for control
- Card with 8 digital outputs expandible to hundreds (used 3)
- Card with 4 analog, 5 digital inputs and expandible to dozens (used 2)
- Firewire card for camera data acquisition. 400Mb/s

▪ Total cost = 2600€,  
Including UST\_1 core, vacuum , e-gun and control system, but not work.



Work not included Cost, incl. transport	€ (Euros)
Vacuum vessel + frame for coils	61
Conductor	75
Power supplies + main leads + switch	206
Mechanising device (only paid elements)	222
Diagnostics : e-gun + RGA + spectroscope	441
Vacuum system	1610

# UST\_1 installation



Whole installation. Two PC's for data acquisition and control are out of the image

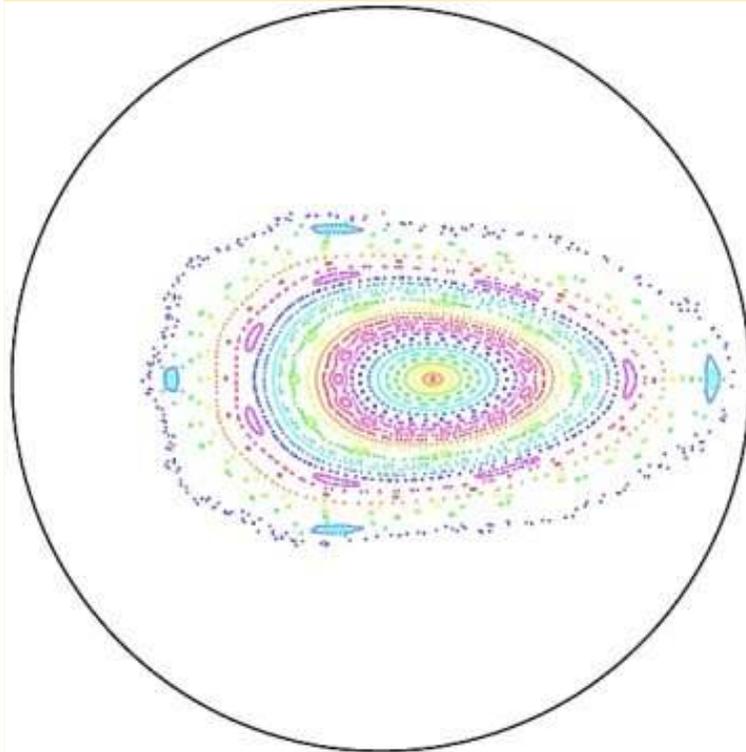
## Calculated expected parameters

- UST\_1 project is focussed in **engineering**
- The **physics calculations** are only **estimates** and optimization (in the next pages) is poor in spite of the effort
- Parameters are very modest, similar to any small and/or low B stellarator

	Expected values	Observations and conditions
$n_e=n_i$	order of $10^{17} \text{ m}^{-3}$	Limited by $\tau_E \sim P$ heating and cut-off freq. ECH
$\tau_E$	3,4 $\mu\text{s}$	ISS04 , e.f. = 1, $n= 1 \times 10^{17} \text{ m}^{-3}$ , $P=400\text{W}$ , 0.1T
$\tau_E$	0,15 $\mu\text{s}$	More real : e.f.=0.1, 0.04T
$\tau_{Ep}$ $\tau_{Ee}$	?? (480 $\mu\text{s}$ ) ?? (4400 $\mu\text{s}$ )	SimPIMF v2.5 (initial, not contrasted) , $T_e = 2\text{eV}$ , $T_i=0.5\text{eV}$ , $n= 1 \times 10^{17} \text{ m}^{-3}$ , Only neocl. flux particles
$T_e \text{ max}$	order of 2 eV	$n = 2 \times 10^{17} \text{ m}^{-3}$ , $T_e = T_i$ , $P=400\text{W}$ , e.f.=0.1 , 0.1T
$T_i$	< 2 eV, ~0.2-0.5eV	Due to $\uparrow$ drifts per tor. turn $\rightarrow$ direct losses
$\sim\beta$	$\sim 0$ , <0.01%	$n= 1 \times 10^{17} \text{ m}^{-3}$ , $T_e = T_i = 2\text{eV}$ , 0.1T , $\sim$ WEGA

**Section III . SimPIMF code  
and Optimization of coils**

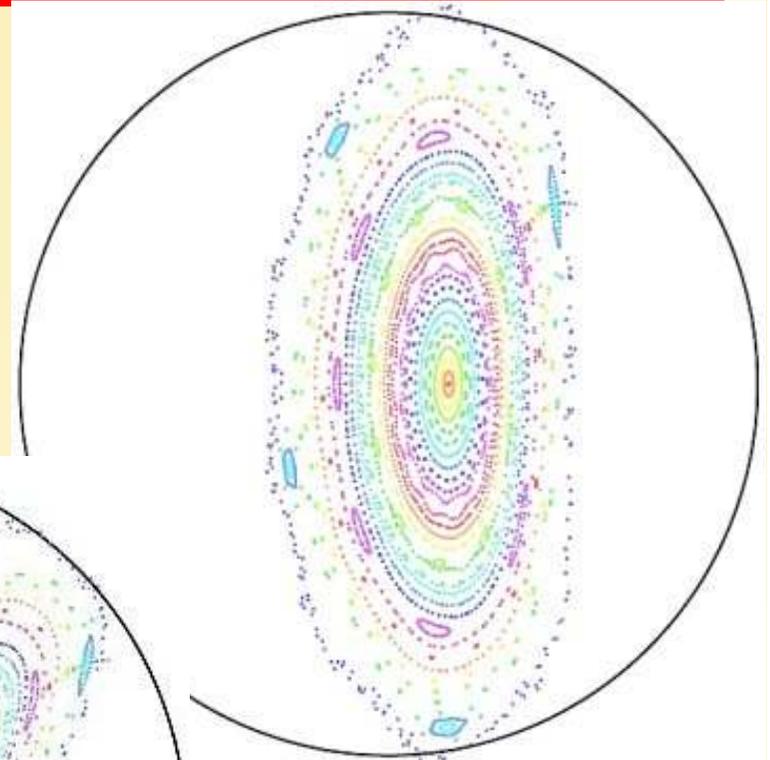
# Simulated magnetic surfaces in UST\_1



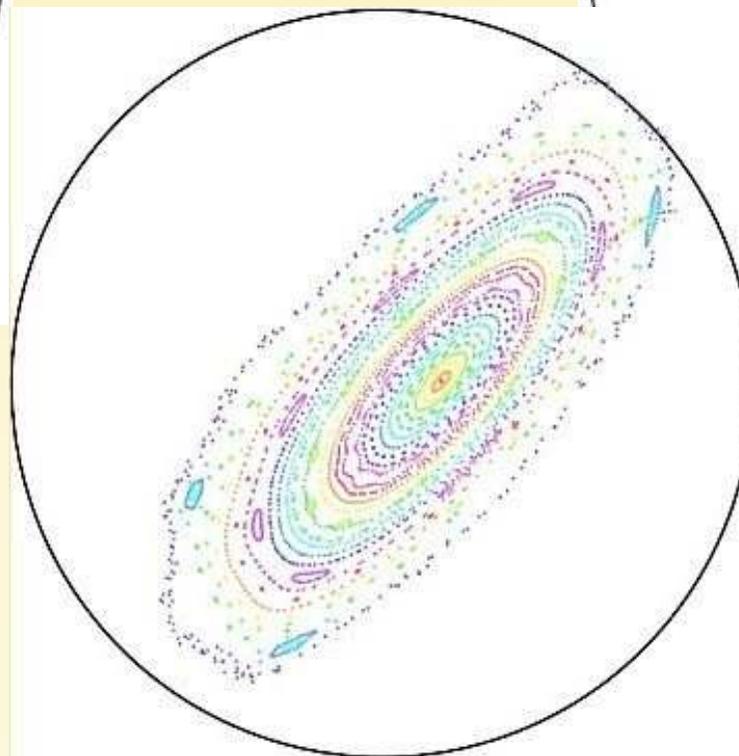
$\Phi = 0^\circ$

Vacuum magnetic surfaces. Poincaré plots. Simulation without drifts.

SimPIMF code v2.3 is used



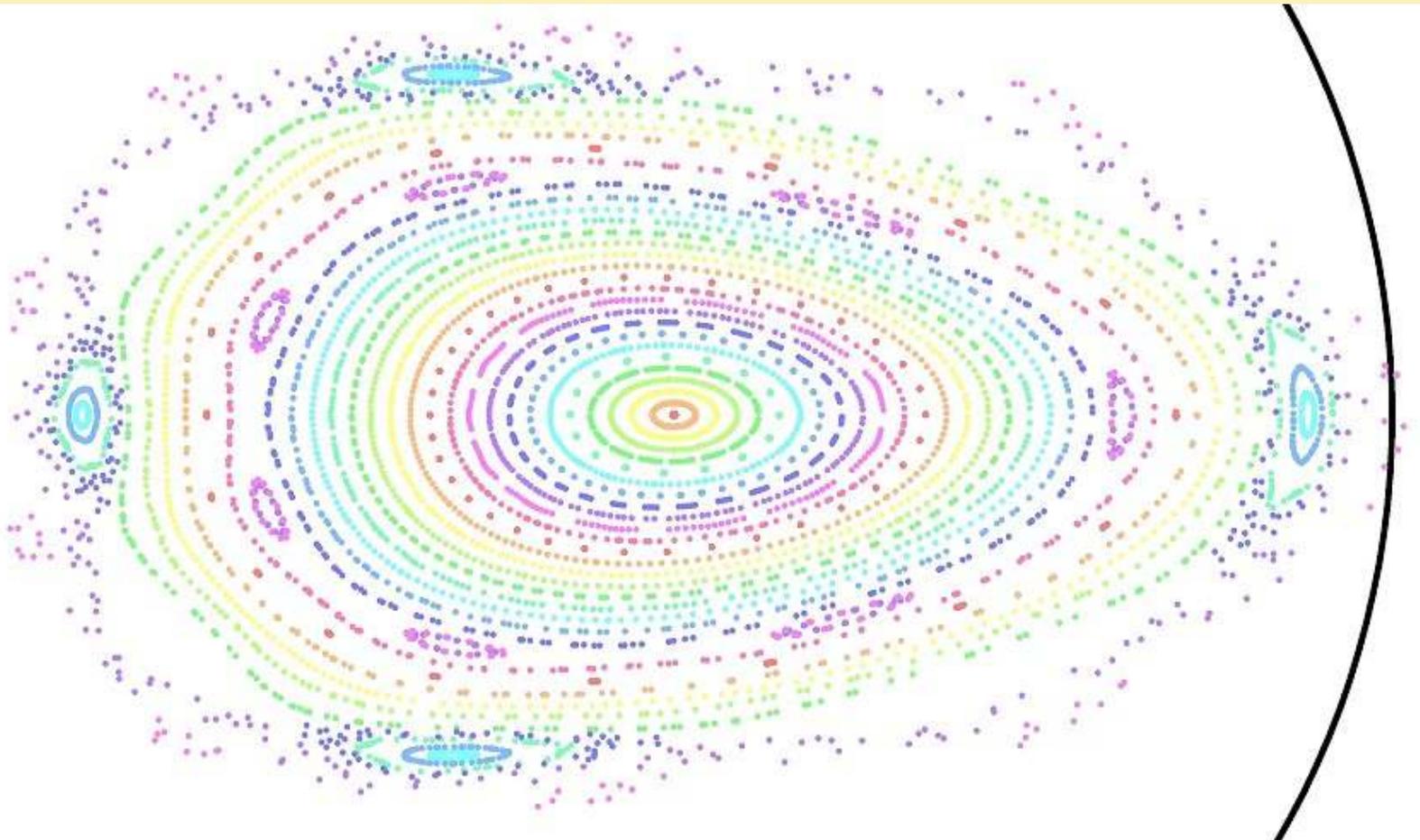
$\Phi = 90^\circ$



$\Phi = 45^\circ$

Note : The black circumference is the internal surface of the vacuum vessel.

# Magnetic surface in UST\_1



## Rationals:

- **Low order rationals are avoided, except :**
- $2/7 = 0.2857\dots$  in magenta is the higher order but not excessive.
- Blue :  $1/4$  rational, out of the LCFS
- Outer stochastic region

$\Phi = 0^\circ$

**Optimization :** Avoid large islands by tailoring Iota profile below  $1/3$  . Most of the plasma have Iota from 0.32 to 0.27

*Simulation using accurate grid  $1/400m = 2.5mm$  side.*

## General features :

- Developed in **JAVA**
- 15 modules and 8250 lines of code
- Developed from scratch during **1.5 years** according to needs and knowledge
- **Output are files** which can be easily transferred or represented by many codes
- **Object oriented** code easily expansible and very suited to this style of simulation

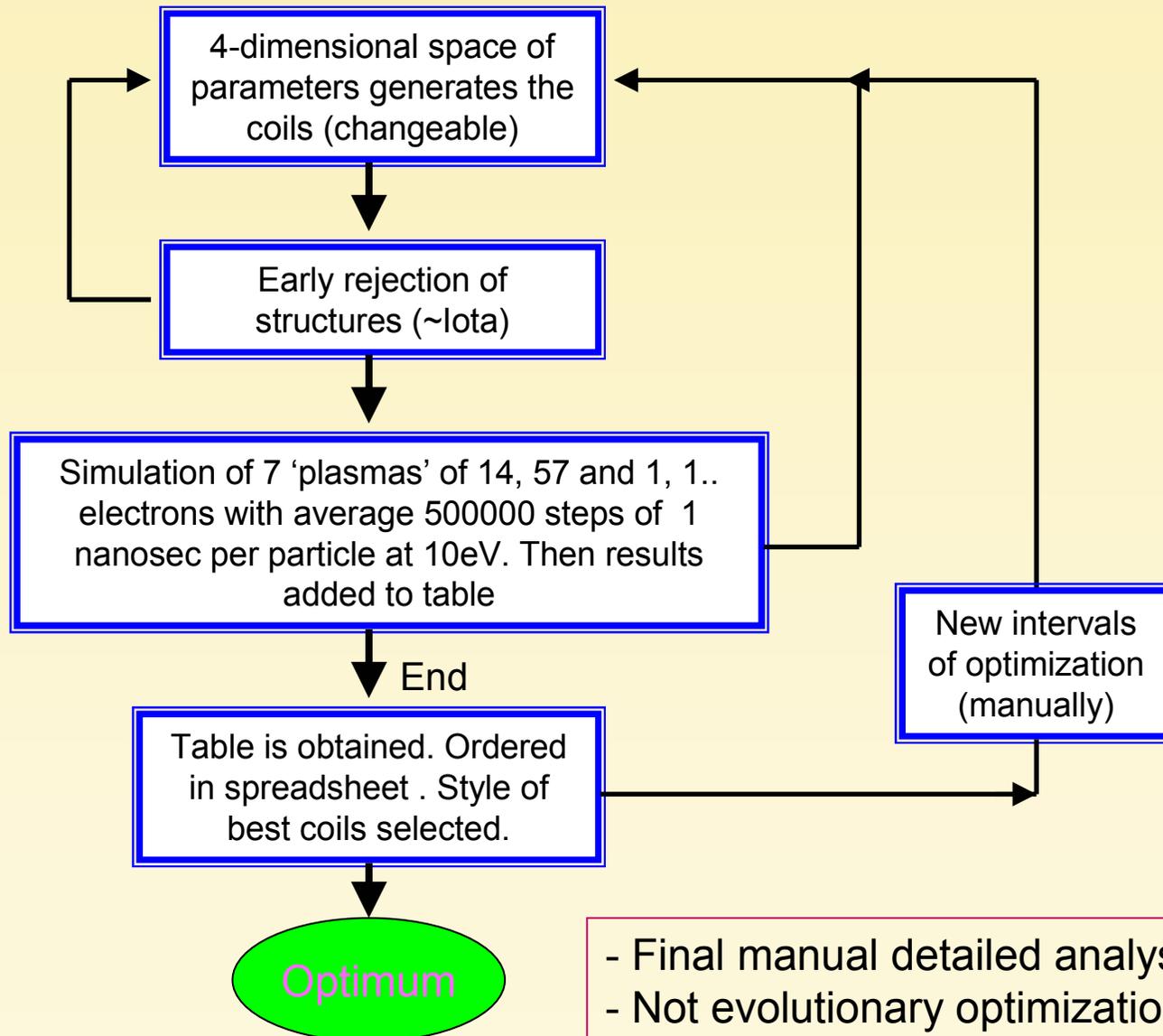
## Functions and methods:

- a) B in 3D . (Forces 3D not in JAVA)
- b) Simulation of orbits with and without drifts, Larmor, E field(slow)
  - Outputs: Iota profile , Magnetic Well profile, Ripple and Averaged ripple, Plasma Size,  $\delta$  |B|<sub>min</sub>, % of trapped particles, Min. distance among coils, 3D polygon of mag. axis, and magnetic surfaces
- c) Generation of parametric 3D coils : Modular 'circular', HF ,TF and PF
- d) Collision simulations. Only first rough results, little contrasted

## Validation and tests

- a) Tested by calculation of fields and forces in EAST and CTH coils
- b) Field mapping in UST\_1 (agreement, but still weak test). Banana widths.
  - Each output needs further comparison with other codes and experiments

# Optimization of coils



## Features and drawbacks

- **Fast** simulation of each orbit.
- The early selection speeds up the process.
- **Time consuming** if more than 4 parameters
- 6 to 27 PC-hours for **~6000 structures of coils**
- However this optimization is mostly **useful in final steps** after a NESCOIL-like run, similar to COILPLOT method.

- Final manual detailed analysis of optimum
- Not evolutionary optimization but easy to implement

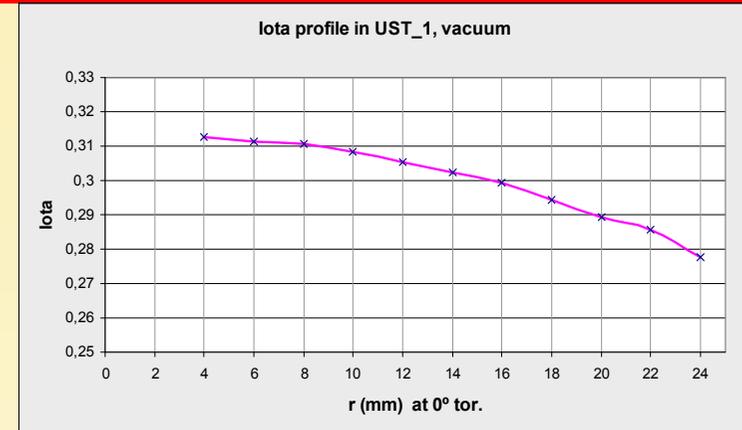
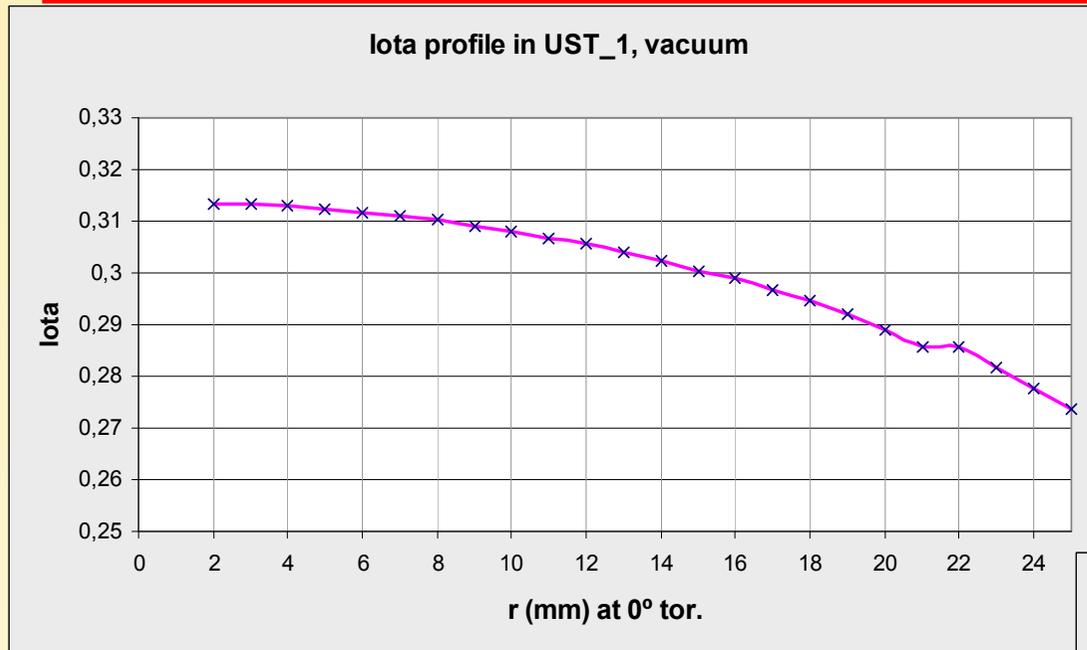
# Optimization . Table of results

Order	Iota_1	Ripple_1	%T	Bmin_Desvia	Average_Rip	PlasmaSiz	Iota_2	Speci	Speci	MinDistanc	Fr	Pitch_On	Pitch2	Pitch3	Pitch4	H	Positi	up/dwon	well	
5	0,32121037	0,21300687	0	0,00374385	0,11439581	0,05125	0,33552672	9,98	10	0,009852	0	1,4	1,25	1,6	0,65	1	0,13	1,045	0,005	
73	0,32177544	0,19787124	0	0,00318734	0,11406053	0,05	0,33412121	9,75	9,82	0,007882	0	1,5	1,35	1,55	0,6	1	0,13	1,038	0,007	
65	0,32024554	0,20227083	0	0,00373036	0,10963253	0,05125	0,33327691	9,59	9,7	0,008333	0	1,5	1,3	1,55	0,65	1	0,13	1,041	0,011	
66	0,31997029	0,21509815	0	0,00312266	0,11926719	0,05125	0,33323999	9,88	9,96	0,008333	0	1,5	1,3	1,6	0,55	1	0,13	1,041	0,008	
58	0,31962951	0,21167492	0	0,00411215	0,11538991	0,05125	0,33303551	9,76	9,81	0,008784	0	1,5	1,25	1,6	0,6	1	0,13	1,042	0,006	
100	0,32221723	0,20706325	0	0,00441405	0,11215376	0,055	0,33275596	9,55	9,68	0,007348	0	1,55	1,35	1,55	0,6	1	0,13	1,033	0,013	
21	0,31750303	0,22302173	0	0,00378824	0,12245854	0,05	0,33218611	10,2	10,3	0,00895	0	1,4	1,35	1,6	0,55	1	0,13	1,046	0,002	
38	0,31735654	0,21121886	0	0,00379767	0,11032161	0,0525	0,33182238	9,74	9,83	0,008867	0	1,45	1,3	1,55	0,65	1	0,13	1,046	0,009	THIS
46	0,31811712	0,20618378	0	0,00347575	0,11421107	0,0525	0,33172369	9,91	9,94	0,008416	0	1,45	1,35	1,55	0,6	1	0,13	1,043	0,004	
31	0,31552703	0,22044592	0	0,0037769	0,1160773	0,05125	0,33076228	9,89	9,98	0,009318	0	1,45	1,25	1,6	0,6	1	0,13	1,048	0,009	
39	0,31629678	0,22423351	0	0,00345106	0,12014642	0,0525	0,33013713	10	10,1	0,008867	0	1,45	1,3	1,6	0,55	1	0,13	1,044	0,006	
84	0,31663715	0,2027263	0	0,00370281	0,11769417	0,055	0,32961367	9,7	9,78	0,008056	0	1,55	1,25	1,6	0,55	1	0,13	1,041	0,009	
91	0,31780244	0,19299761	0	0,00414231	0,11246796	0,05375	0,32909387	9,54	9,63	0,00778	0	1,55	1,3	1,55	0,6	1	0,13	1,036	0,009	
99	0,31631804	0,20671245	0	0,00468787	0,11574988	0,055	0,32851403	9,66	9,76	0,007348	0	1,55	1,35	1,55	0,55	1	0,13	1,039	0,011	
83	0,3154783	0,19315352	0	0,00436111	0,10875171	0,0525	0,32830247	9,39	9,51	0,008056	0	1,55	1,25	1,55	0,65	1	0,13	1,041	0,013	
11	0,31369671	0,21665571	0	0,00410095	0,11192947	0,05125	0,32827982	9,9	9,98	0,009401	0	1,4	1,3	1,55	0,65	1	0,13	1,046	0,007	
4	0,31422598	0,2092244	0	0,0035935	0,11873827	0,05125	0,32806725	10	10,1	0,009852	0	1,4	1,25	1,6	0,6	1	0,13	1,044	0,006	
19	0,31346058	0,21258333	0	0,00432119	0,11584367	0,05	0,32744505	10,1	10,1	0,00895	0	1,4	1,35	1,55	0,6	1	0,13	1,045	0,003	
Cut																				
90	0,30859755	0,21014439	0	0,00433755	0,11578788	0,055	0,32115361	9,61	9,69	0,00778	0	1,55	1,3	1,55	0,55	1	0,13	1,041	0,009	
63	0,31314478	0,20095219	0	0,00297516	0,1167087	0,05625	0,32018027	9,75	9,83	0,008333	0	1,5	1,3	1,55	0,55	1	0,13	1,022	0,008	
18	0,30694923	0,2152499	0	0,00340183	0,12000274	0,0525	0,32006331	10,1	10,2	0,00895	0	1,4	1,35	1,55	0,55	1	0,13	1,043	0,007	
55	0,30714644	0,20132164	0	0,00371561	0,1123814	0,05375	0,31927263	9,61	9,72	0,008784	0	1,5	1,25	1,55	0,6	1	0,13	1,039	0,012	

Table for the last loop of fine intervals of parameters for UST\_1

- The option marked with 'THIS' was the final selection for UST\_1
- Optimization of Iota, Iota profile, Plasma Size, |B|min, Magnetic Well, Averaged Ripple, min. distance between coils
- Only 4 parameters and 7 variables to optimise, so not easy final decision
- More extended simulations necessary to obtain a better design

# *lota and Magnetic Well in UST\_1*

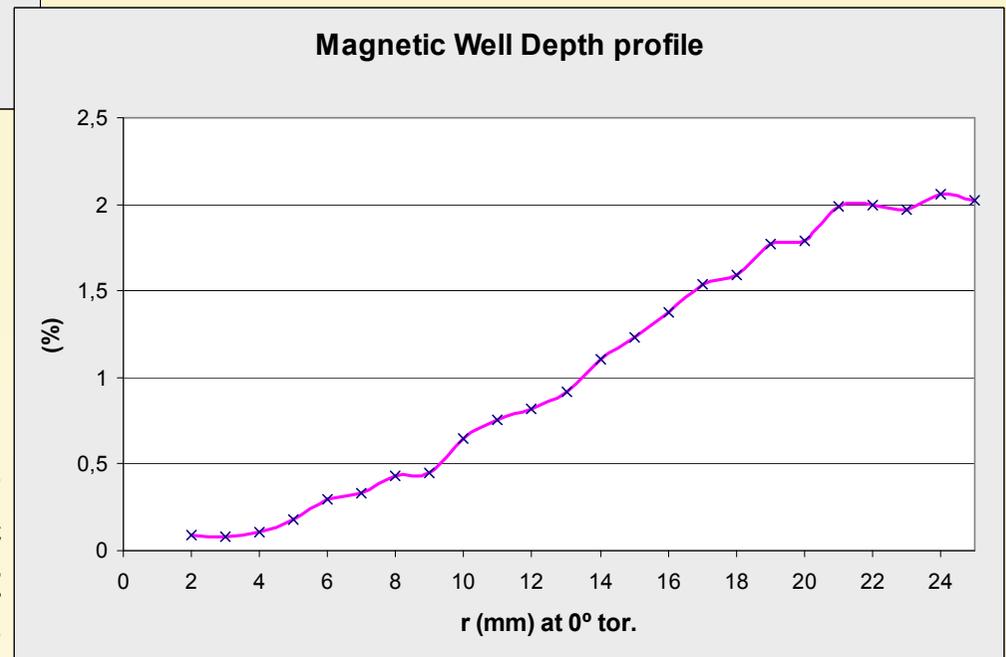


B) lota Fast calculation, 90 s . Similar to A)

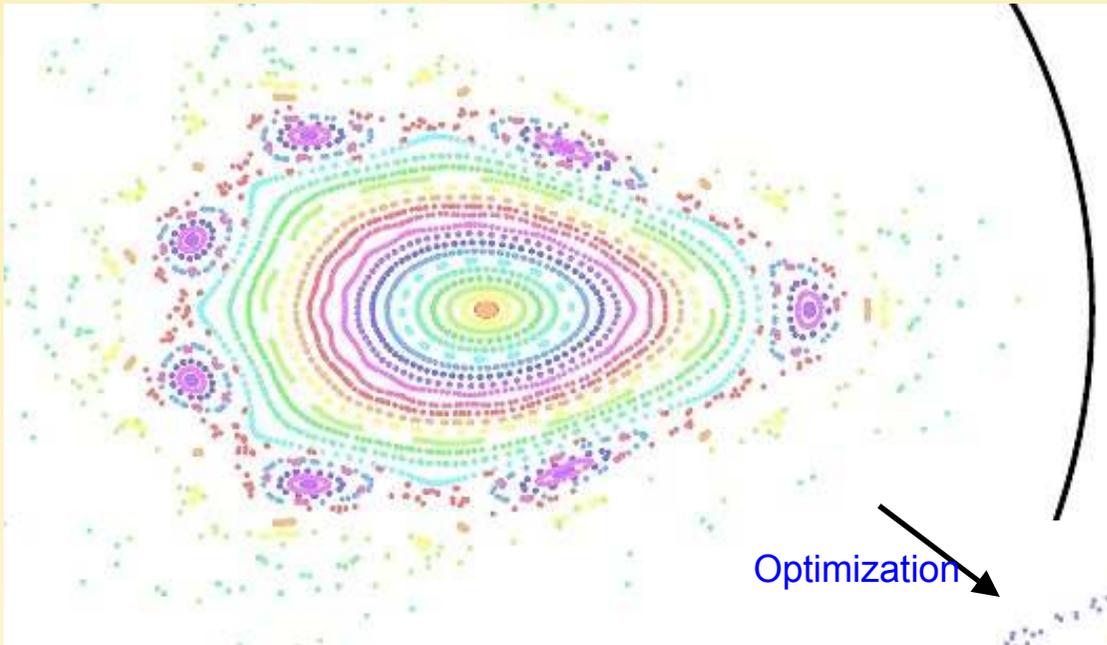
- A) lota profile : Accurate simulation
- **Low Shear** but not low enough
  - **Decreasing lota**. Not OK, but SimPIMF was unable to obtain increasing profiles. ~ MHH2
  - However some flatter cases were found but not considered at that time.

The accurate calculation of lotas + Magnetic Well lasted 1960 s but fast calculation, 90 s

Notable magnetic well , 2% at edge



# Improvements from Optimization

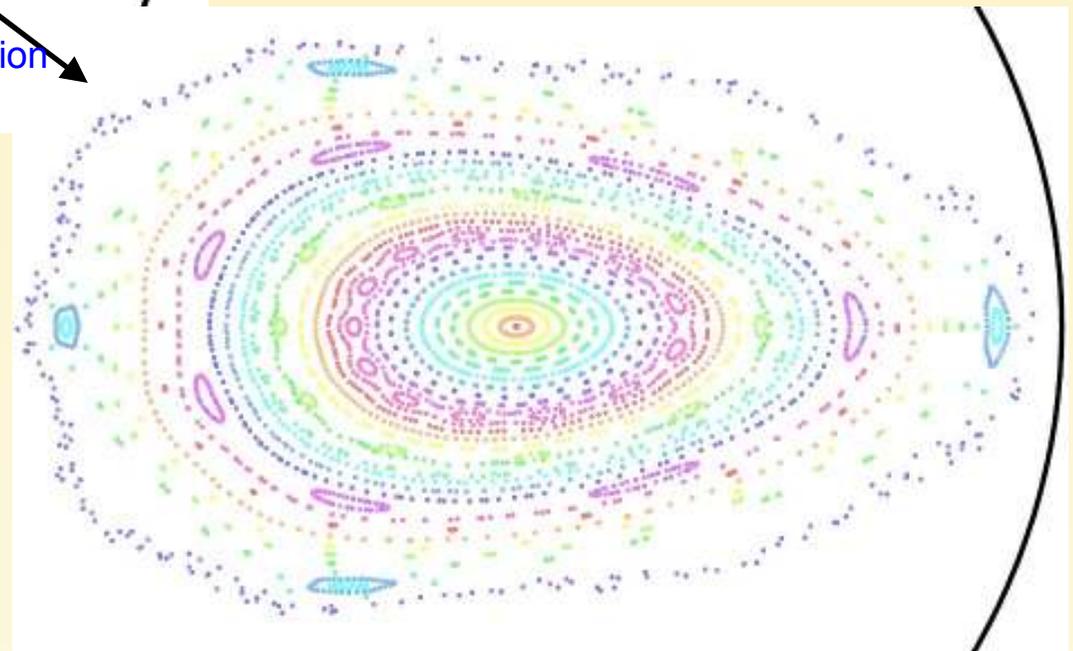


Optimization

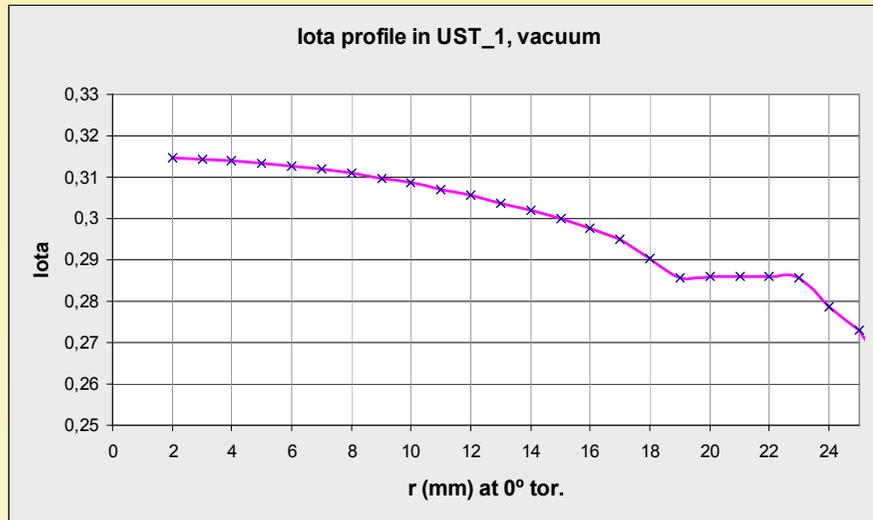
Parameters of shape 1.25 1.25 1.25 1.25  
lota at centre similar to UST\_1

UST\_1 parameters of shape  
1.45 1.3 1.55 0.65

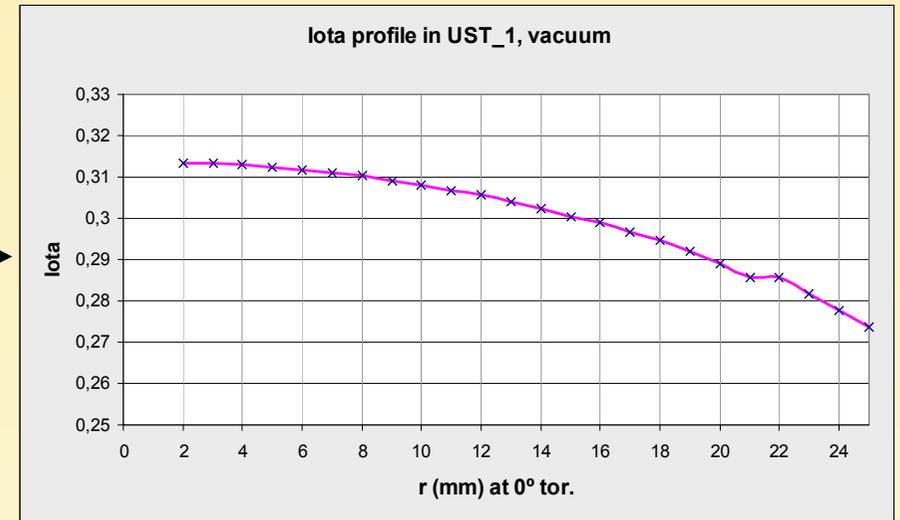
- Larger plasma
- Narrower stochastic region



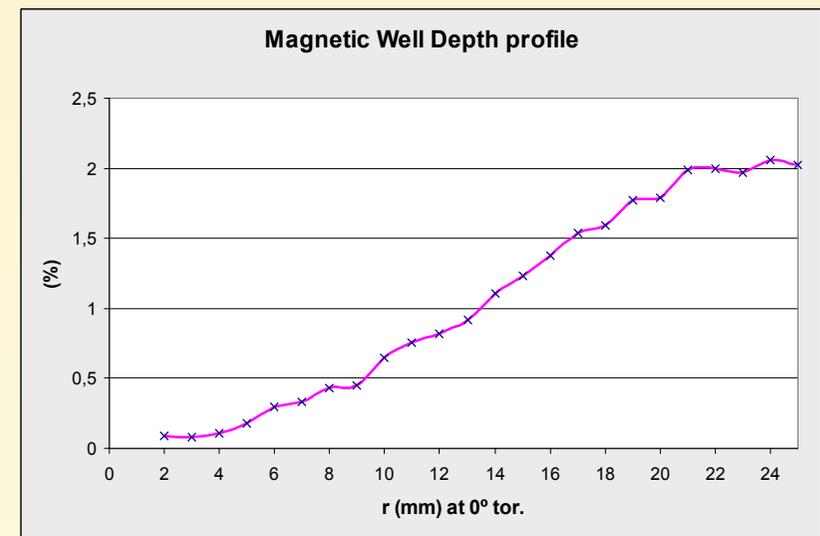
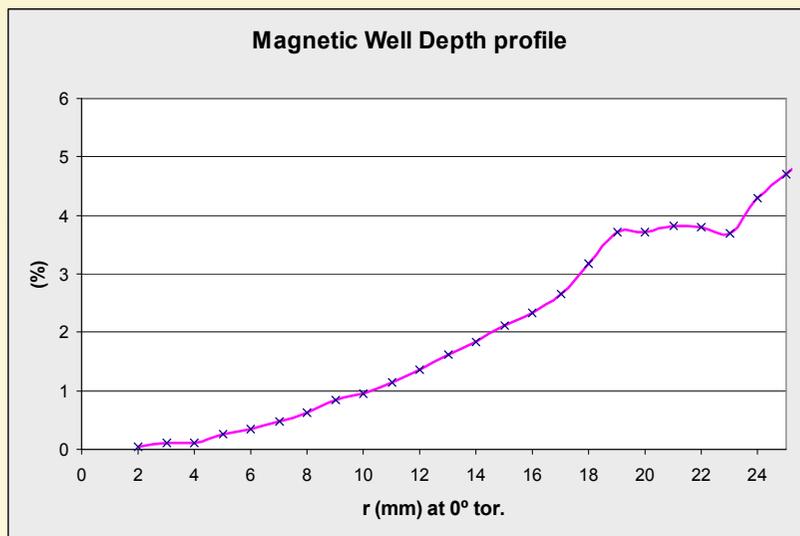
# Improvements from Optimization



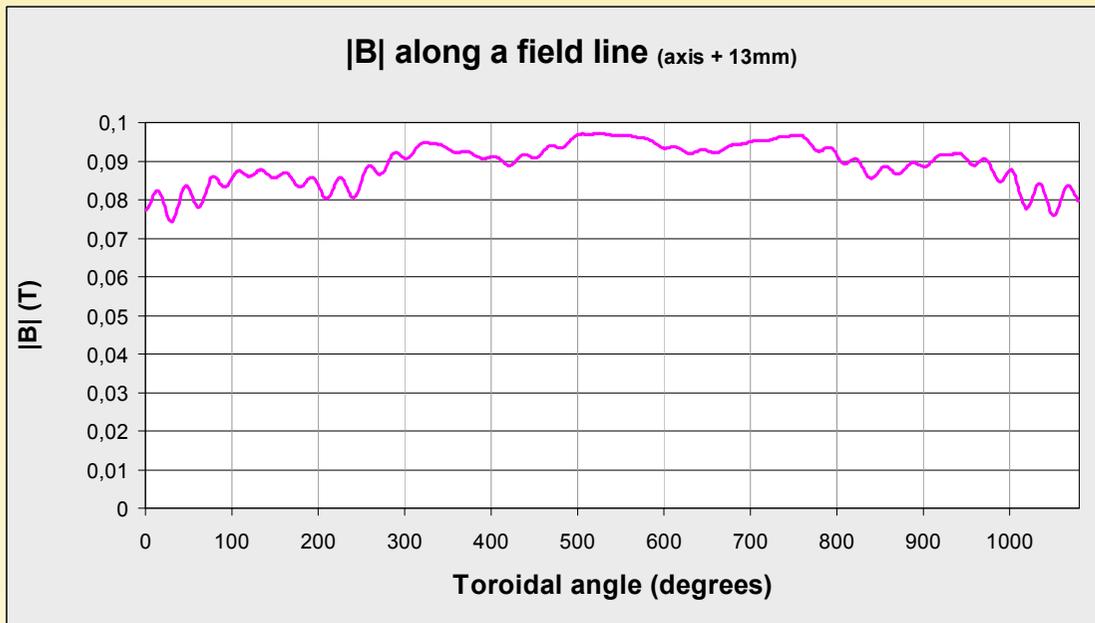
Natural shape : 1.25 1.25 1.25 1.25



UST\_1 shape : 1.45 1.3 1.55 0.65

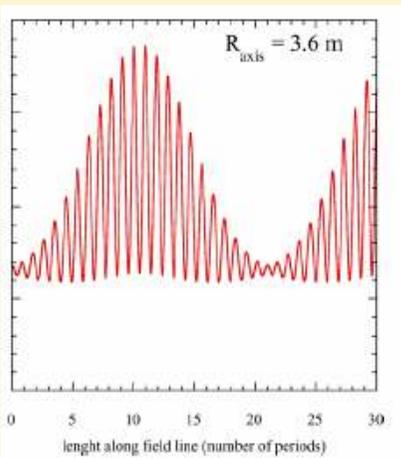


# Other improvements



	4x1.25	UST_1
$\sigma$ Bmin	0.0061	0.0038
Plasma size	0.42 L	1.1 L
Min. dist. coils	6.82 mm	8.9 mm
Ave. ripple	0.08	0.11

Not all variables are the best, for example Magnetic Well is reduced

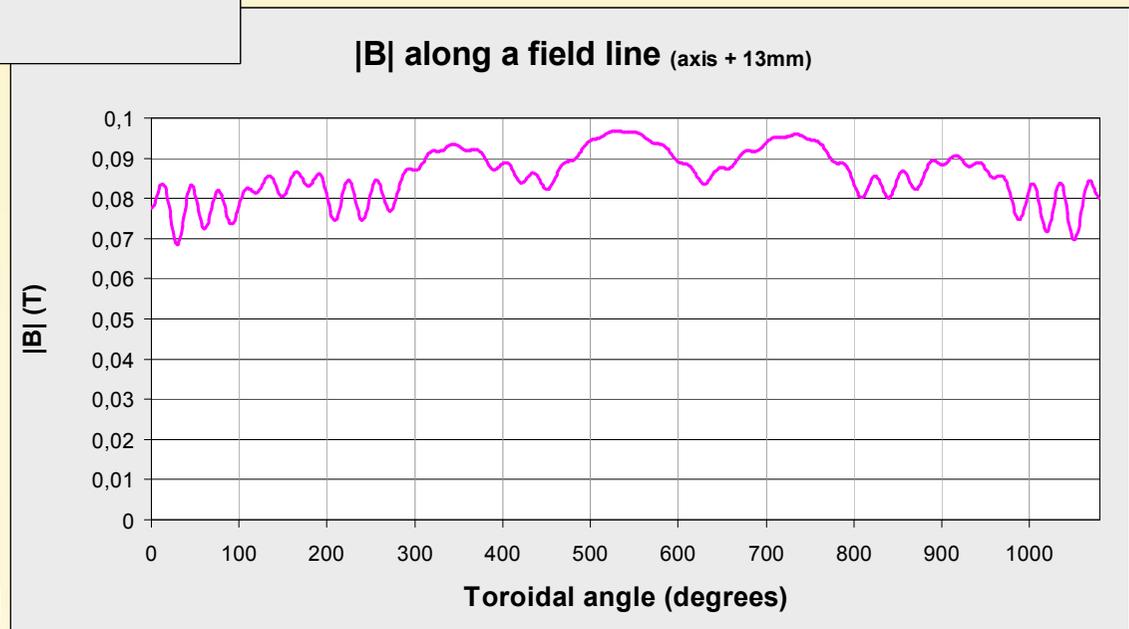


LHD, S. Murakami

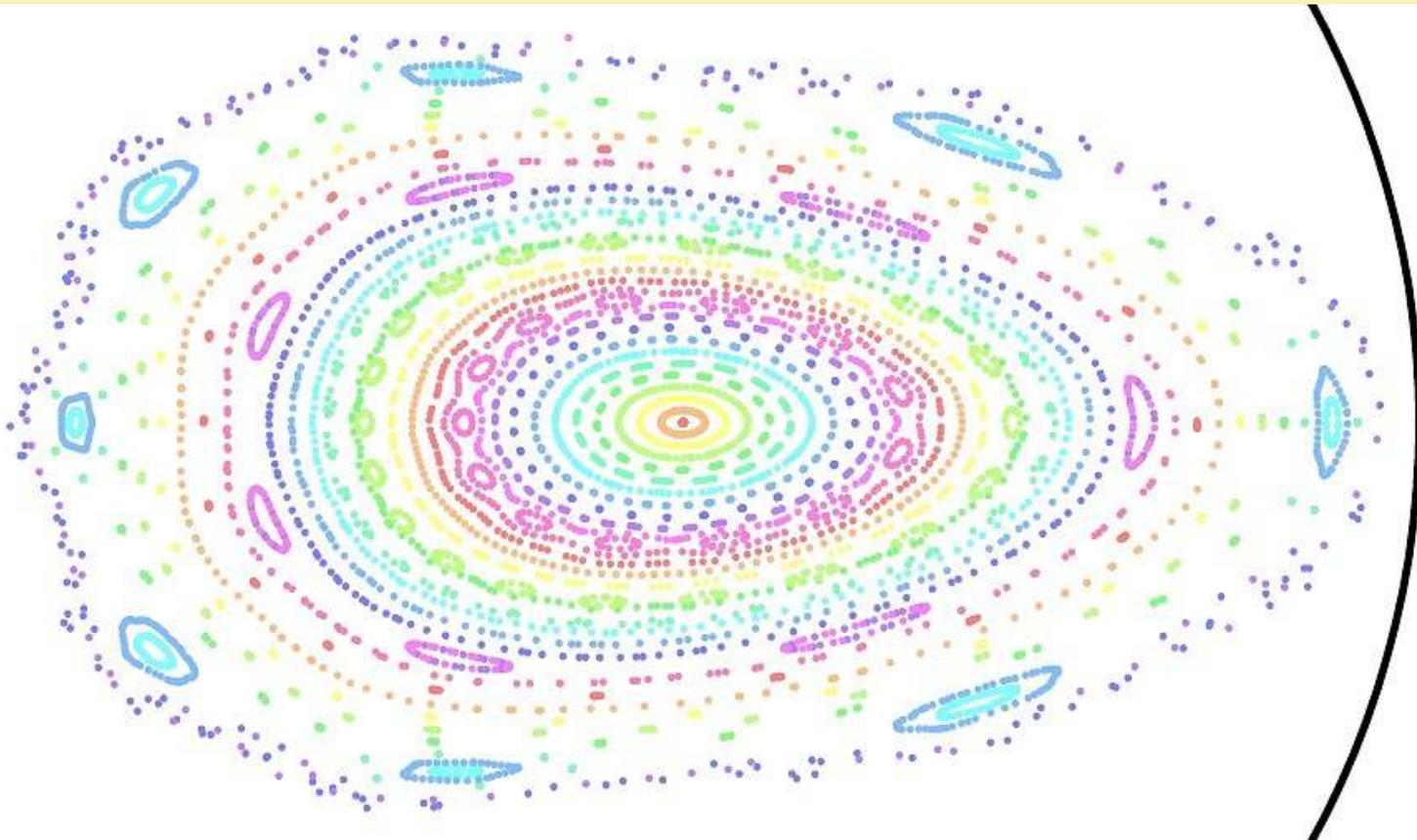
4x1.25 coils

UST\_1 is far from the aim, for example Bmin in LHD improved

UST\_1



# Simulation of Magnetic Islands



## Rationals:

(from right to left)

Blue :  $1/4 = 2/8$

No visible :  $3/11,$   
 $4/15$  ....

Magenta :  $2/7$

Green :  $3/10 = 6/20$

Magenta :  $4/13$

No vis. green :  $5/16$

## Iota accuracy:

Blue :  $1/4$  calculated  
0.2500315

Magenta :  $2/7 = 0.28571$   
, calc. 0.2856076

Green :  $3/10$  calc.  
0.2999538

Each Iota lasted 49 s

$\Phi = 0^\circ$  Some unconnected islands do not appear in the automatic run

**Perturbed B :** Higher  $\delta B$  seems to appear at coarse 'Grid'.  
The figure obtained using grid  $1/200$  m = 5mm side. New  
islands appear.

# The method for FAST simulation

## Original ? :

- Maybe the method is original, BUT
  - there are many codes to simulate orbits.
- In any case it is a fast and useful method.
- **If new**, refer to this Seminar when using it

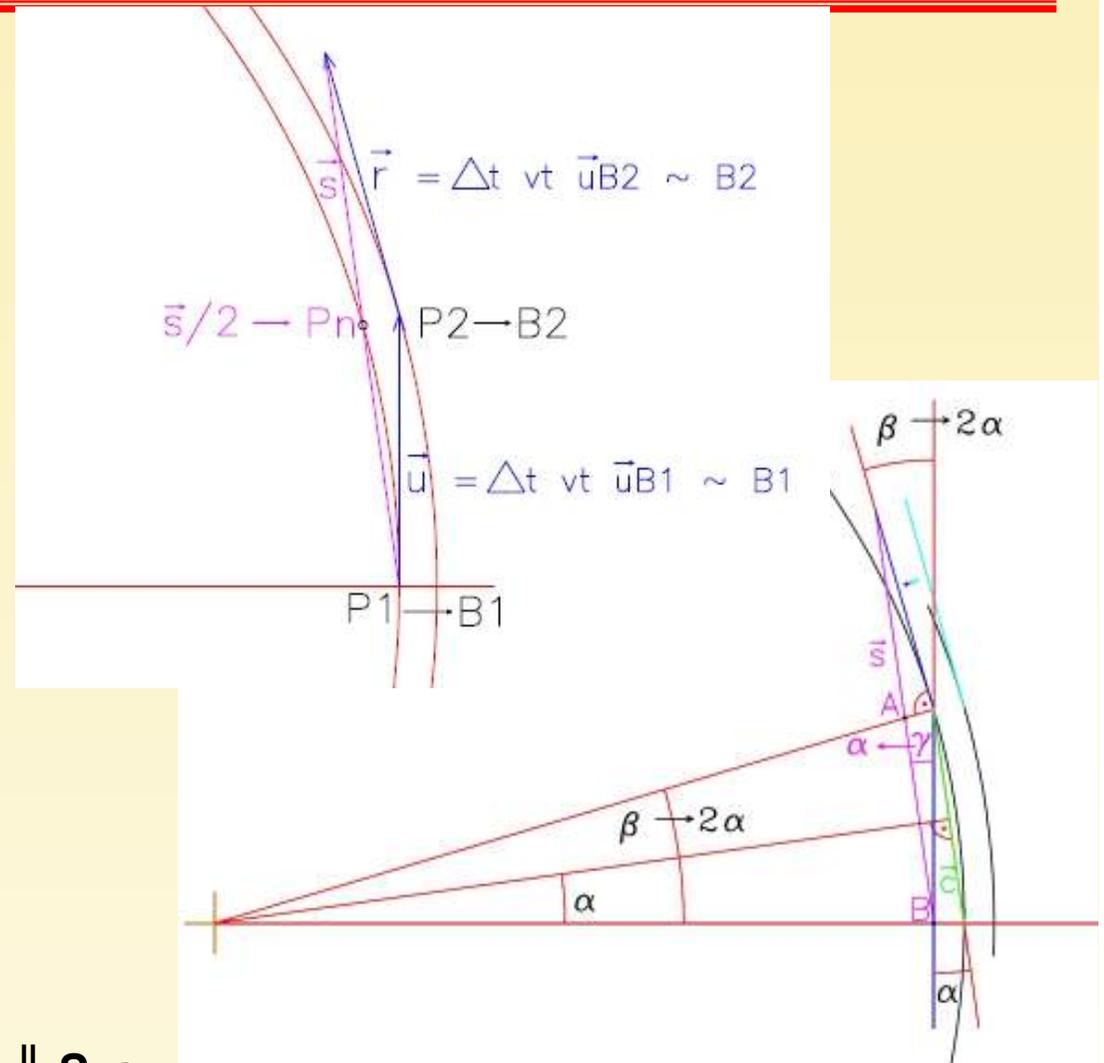
## Advantages :

- It simulates 10-20 times faster than  $dx/Bx = dy/By = dz/Bz$
- Only one PC is enough instead of 20 PC's for the same simulation.
- Simple.
- Probably it can be improved further.

## Hint of the prove :

- A curve can be approximated to a circumference around a point.
- **C** is a Chord ;  $\gamma \rightarrow \beta/2 \rightarrow \alpha$  so **C**  $\rightarrow$   $\parallel$  **S** ;  
 $S/2 \rightarrow AB \rightarrow |C|$

So **S/2**  $\rightarrow$  **C**

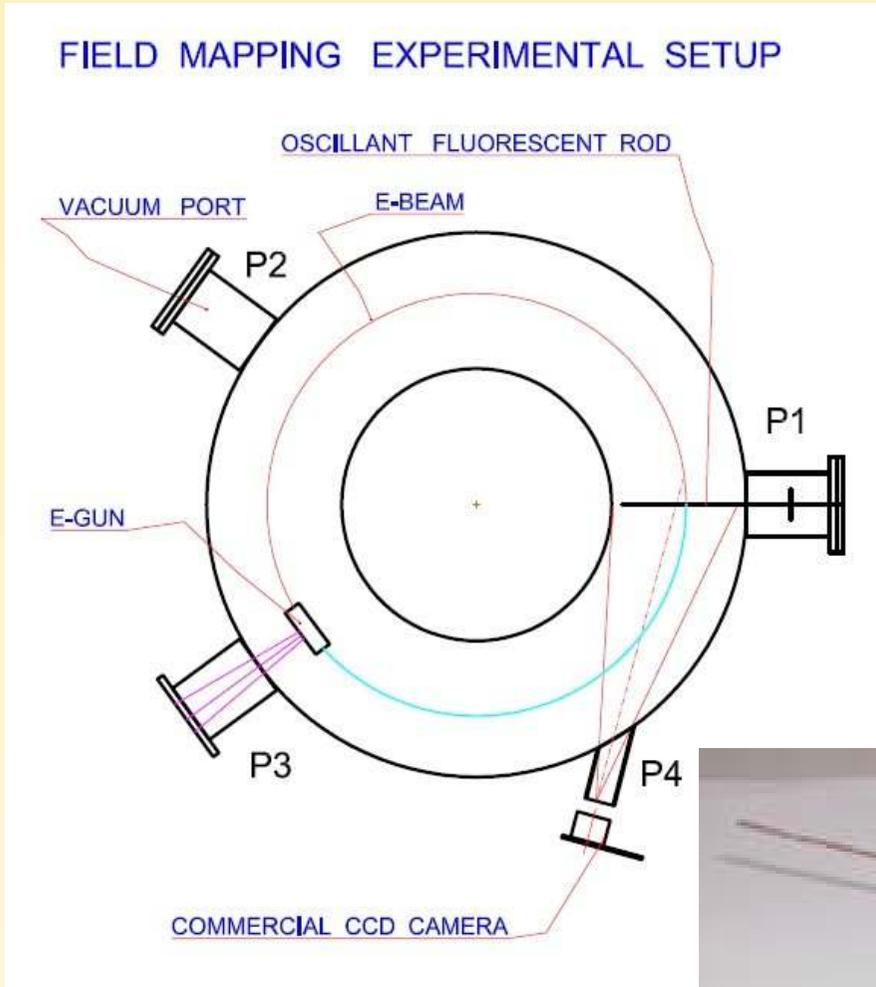


# *Section IV*

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## **Section IV . Experimental results.** Field mapping system and experimental magnetic surfaces

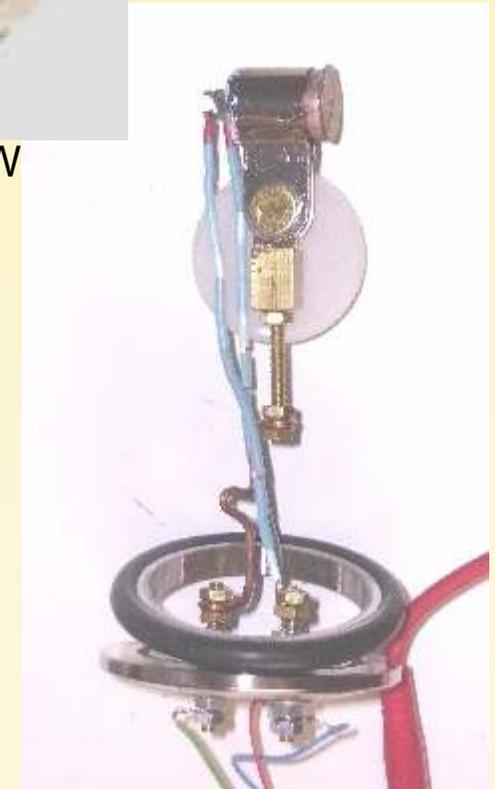
# Field mapping experimental setup



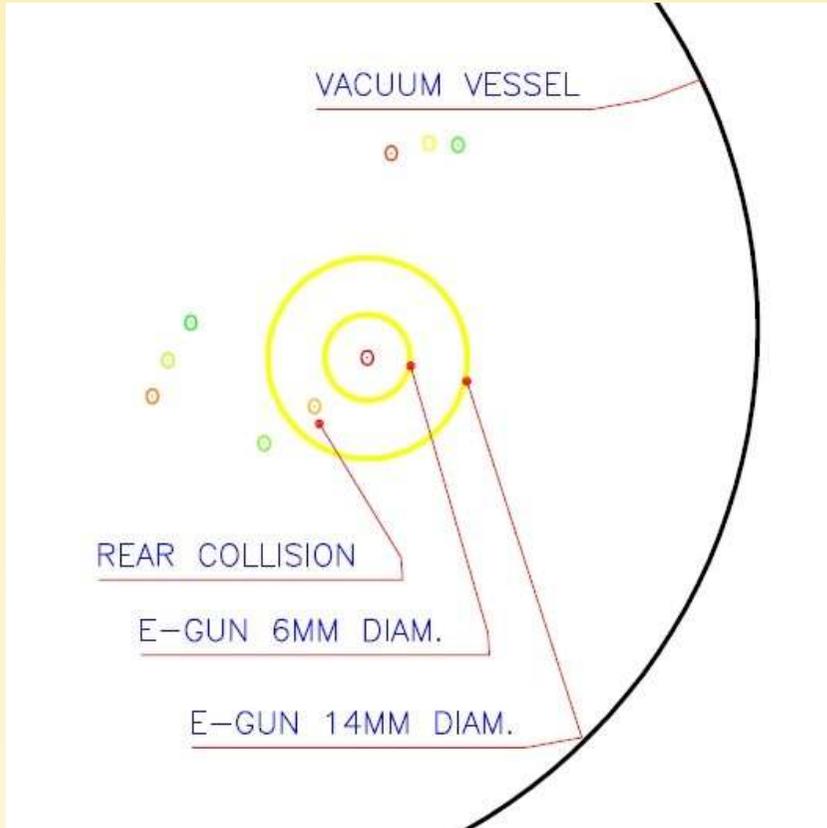
Second model of e-gun :  
External diam.= 14mm .  
e-beam current < 1 mA

Inside : Tungsten filament 10 W

Oscillating fluorescent rod.  
P24 phosphor

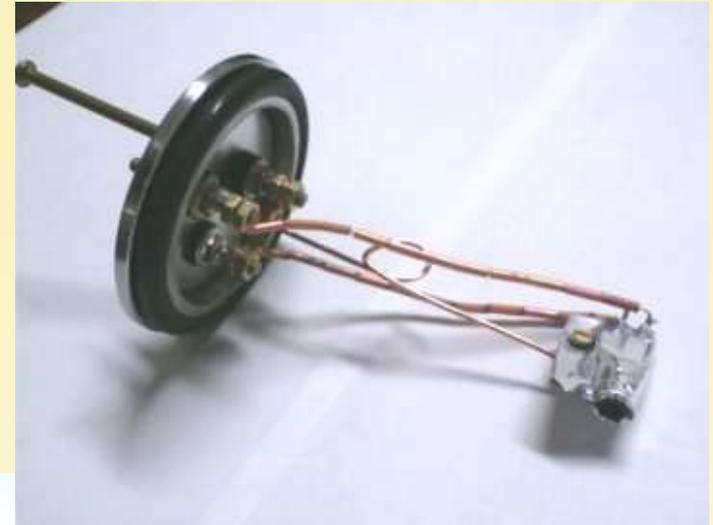
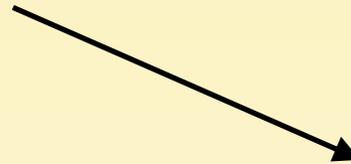


# *e-beam rear collision and solution*



**Rear collision.** Collision of large e-gun after 4 turns. In colours the sequence of intersections of the beam with the e-gun poloidal plane

Very small diameter to see internal surfaces



Third model of e-gun :  
External diam.=6mm .  
e-beam current very low .  
Tungsten filament 10 W

# Background of the experiments

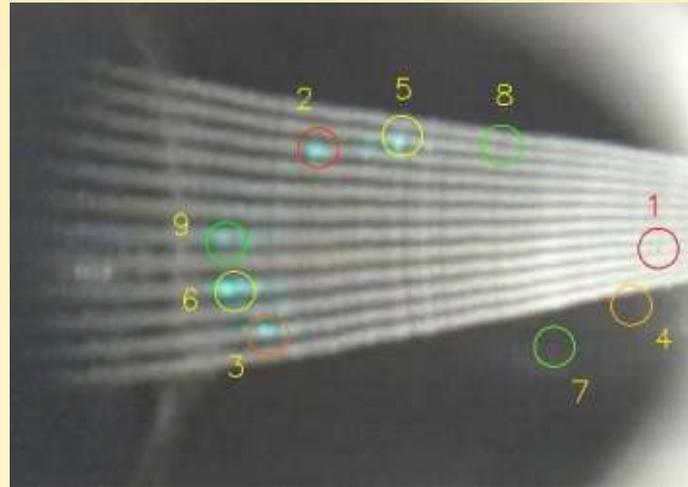
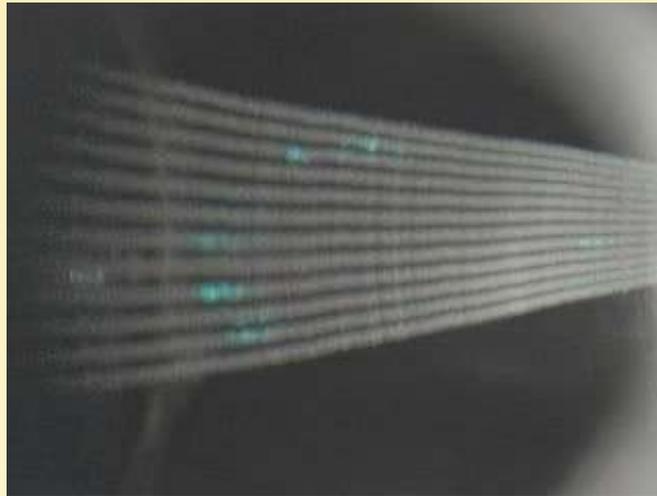
## Background

- The next images were taken at the **pulse #198 and #202** after a long process of improvements.
- The PC-firewire camera is the lowest cost (~quality) in the market, 90€ and the **sensitivity is low. Visual inspection** has far more sensitivity than the camera.
- 40 eV e-beam gave insufficient luminance for both e-guns and only **> 80 eV were visible** with the small e-gun.
- **Drifts at ~90eV are enormous** for UST\_1 ( $B_0 = 34$  mT for these pulses) so the magnetic surfaces are notably displaced outward and  $\iota$  tend to  $1/3$ .

## Background

- **UST\_1 is very small** so the e-beam diam.  $\sim 1.5$ mm is excessive here. Accurate measurements are more difficult than in larger stellarators.
- **Mean free path** at the poor vacuum, 5mPa only allow less than 10 turns of the beam.
- **Pulse length** : 2.5 sec.
- The small e-gun **melt** at the pulse #204 and field mapping ended temporarily.
- **Perspective effect** is only partially corrected.

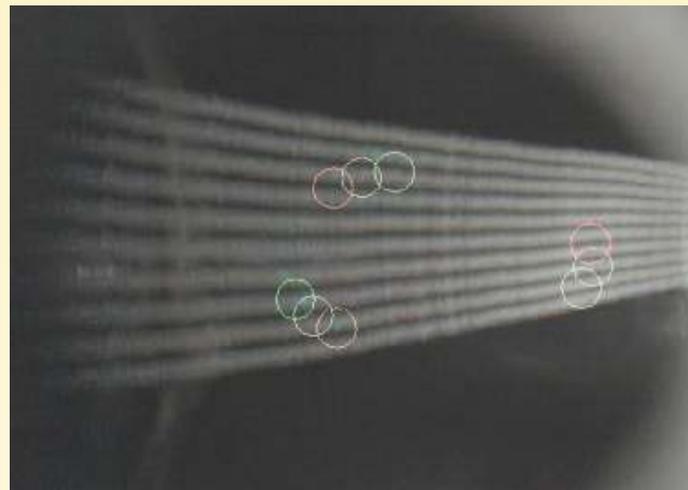
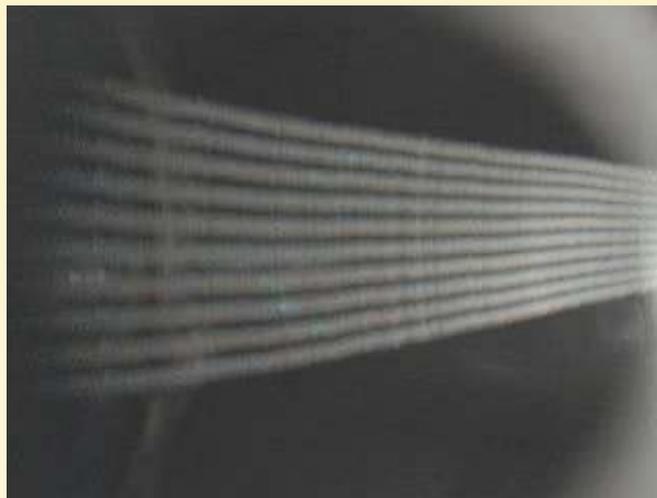
# Comparison simulation-experiences



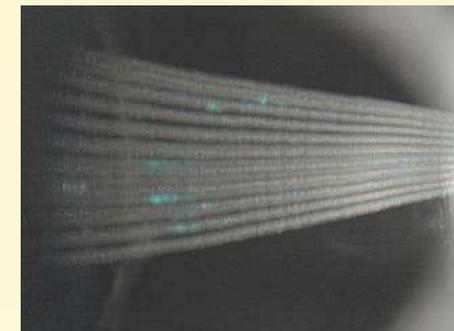
**Pulse #202.** (94eV).  
Simulation obtained locating the e-gun at the approx. real measured position and 94eV electrons (drifts simulation).



N202\_F70-135.mpg

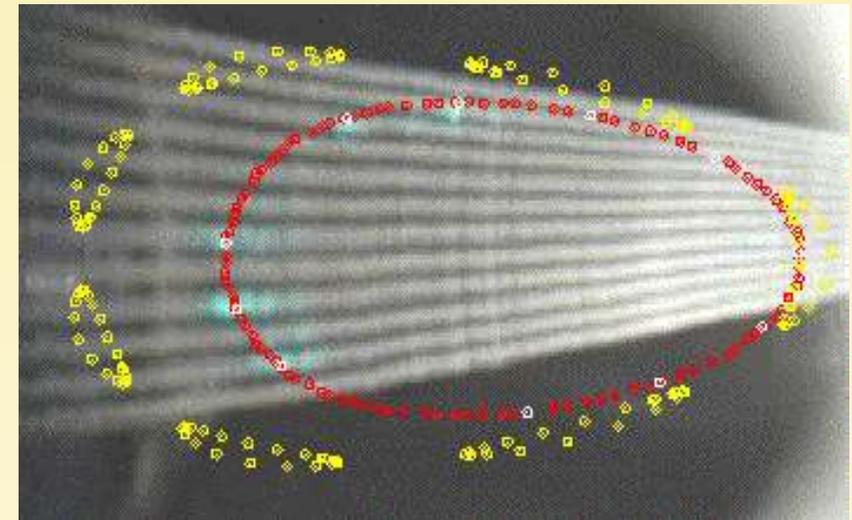
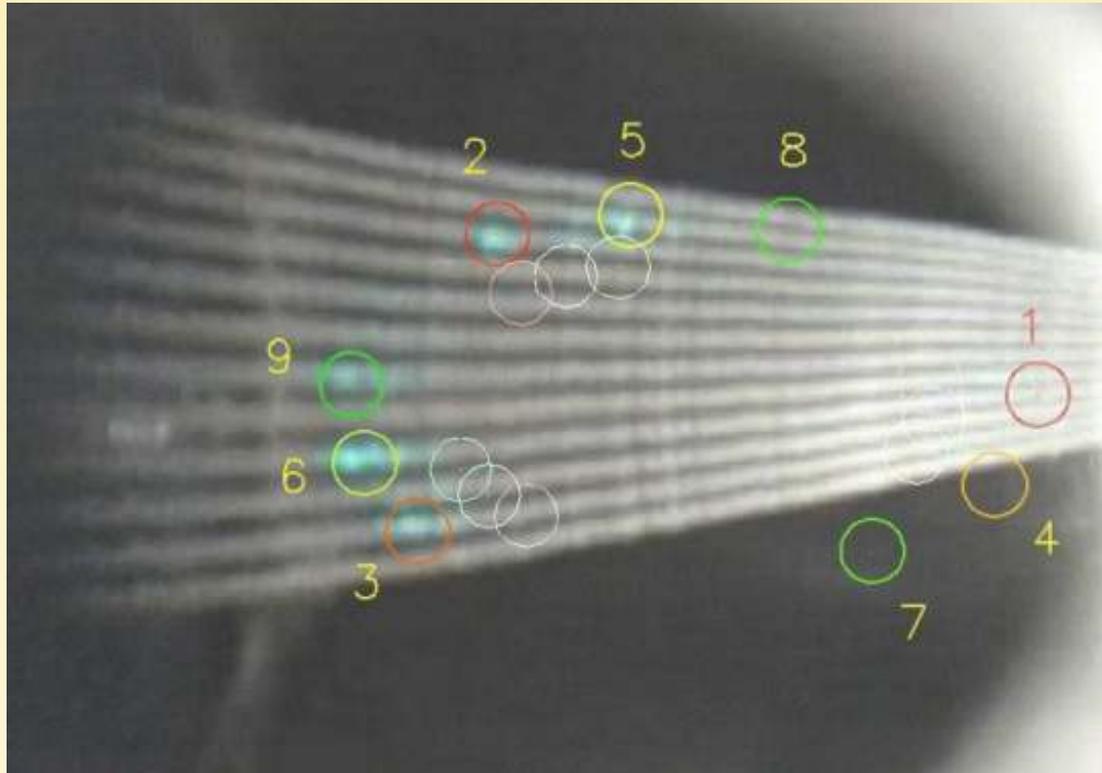


← **Pulse #198.** Weak points (84eV). e-gun 2.3 mm higher than in #202, so internal surface. The e-gun is 'moved' vertically the same distance in the code.



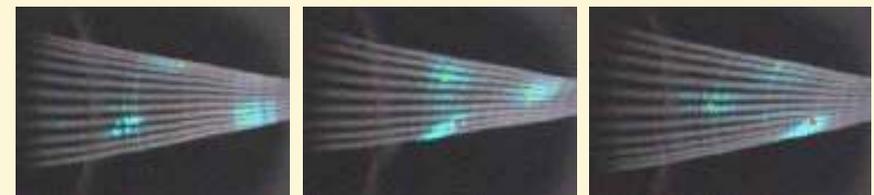
Both pulses overlapped. Weak points → appears even weaker

# Comparison simulation-experiences



Yellow : Non-drift orbit  
Red : Drift orbit = experimental #202

Superposition of all. Two concentric closed magnetic surface appear. Simulated points agree notably well with real points. Superposition reduce the quality of the image and weak points are lost



Other previous pulses, #128 127 126

## *Conclusions from experiments*

Experiments are still few and poor but some provisional conclusions are:

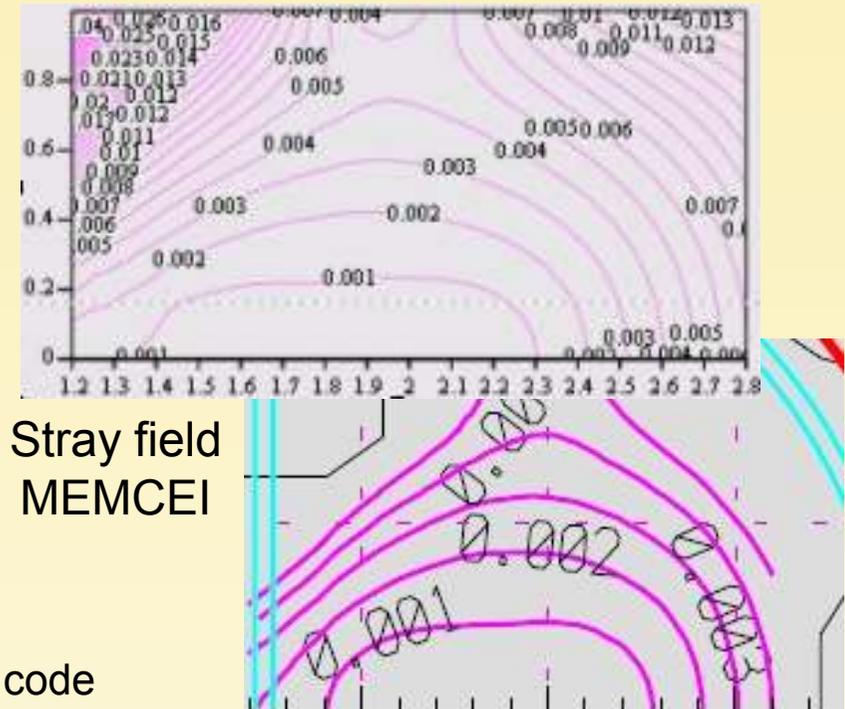
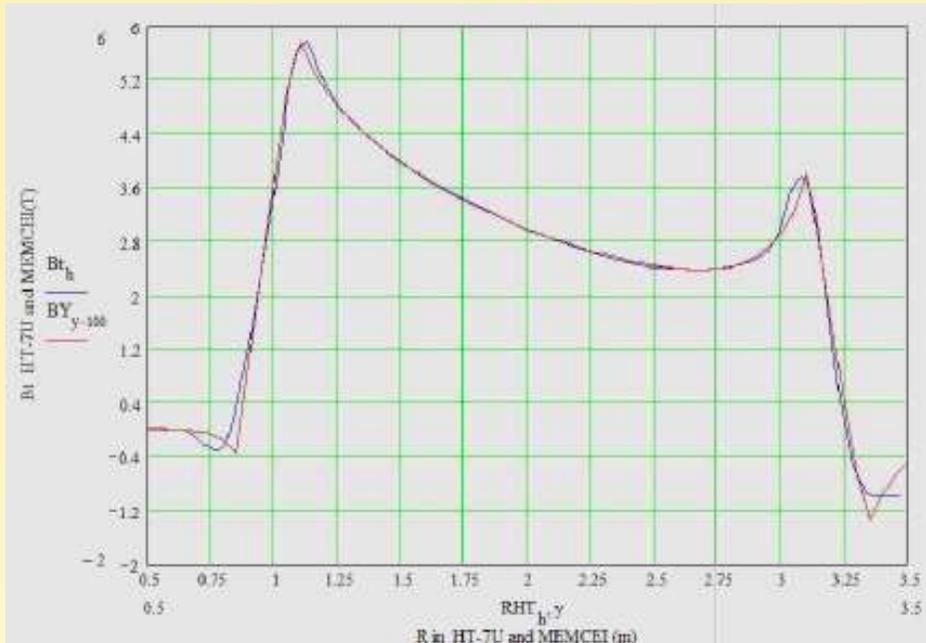
- **UST\_1 has a notable degree of accuracy.** ← Magnetic surfaces are obtained and they agree with the theoretical simulations.
- **The stellarator-mechaniser was a satisfactory idea** ← The toroidal device to mechanise grooves for modular coils worked and produced accurate coils at low cost.
- **SimPIMF code has some degree of accuracy and correction** ← otherwise the agreement between the experimental results and simulations is totally improbable.
- **The optimization was useful and correct in some degree** ← SimPIMF is not totally incorrect.
- **The chosen style of stellarator was a feasible one.**
- **UST\_1 is a stellarator.**

# *Section V*

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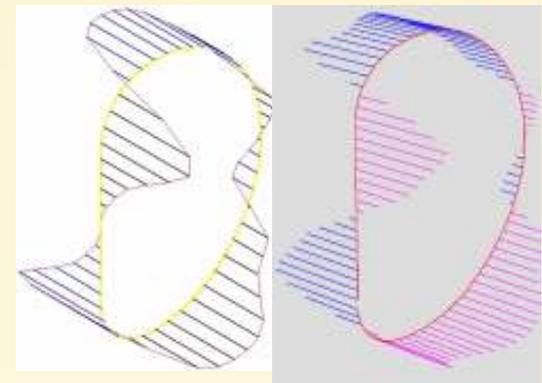
## **Section V . Chronological description : Evolution, alternatives, difficulties and solutions**

# The beginning of fusion calculations

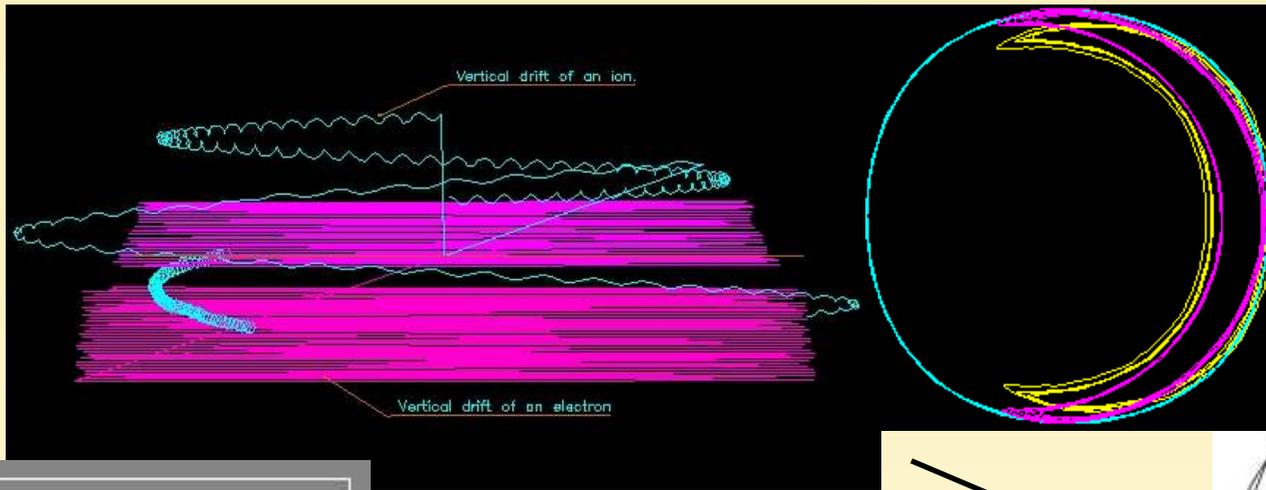


Comparison of Bequatorial in EAST from MEMCEI and EFFI code  
**February 2005** : Using MEMCEI v2.1 , 9440 elements of current, 16 TF coils, 13 loops per TF, 50 ele. per loop Machine : **EAST tokamak (HT-7U)** . Language : **VisualBasic + MC**  
 F centering = **984.3** ton using MEMCEI v2.1 and **989.3** ton with EFFI code (HT-7U team)

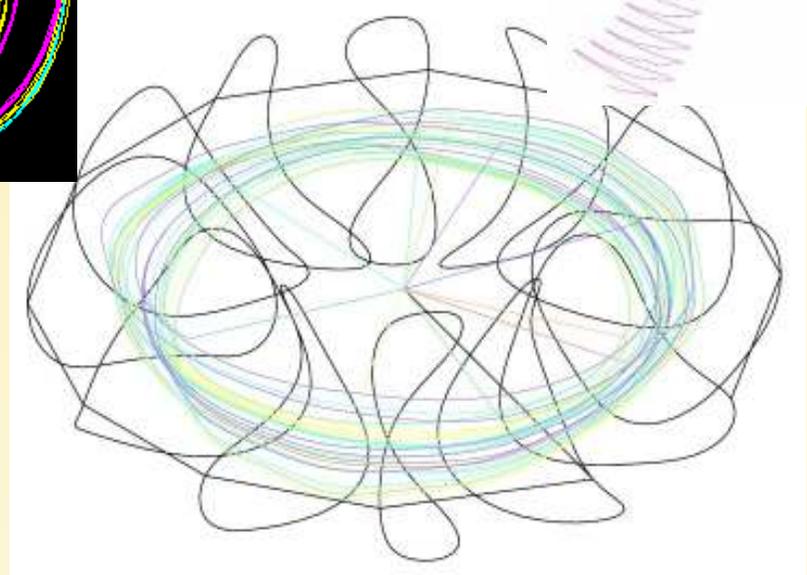
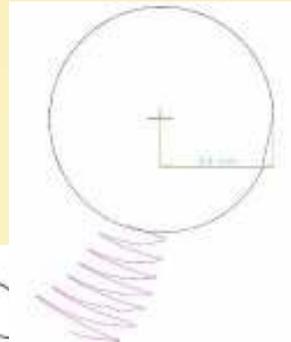
**May 2005 . CTH torsatron** : Calculation of mutual forces between coils using MEMCEI, for Greg Hartwell , Auburn University



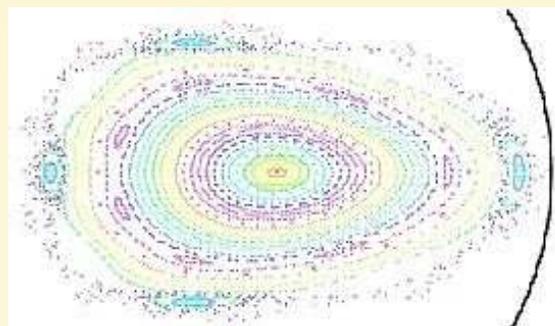
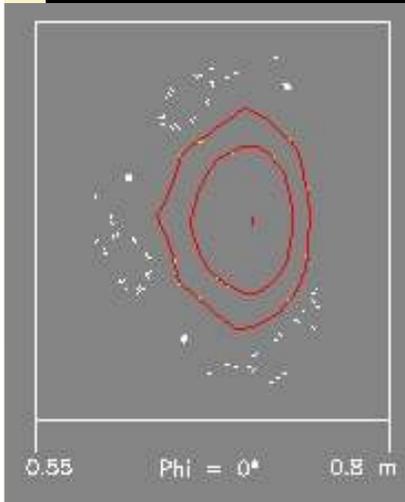
# Evolution in simulation



← March 2006  
Banana orbit in tokamak ~ size UST\_1

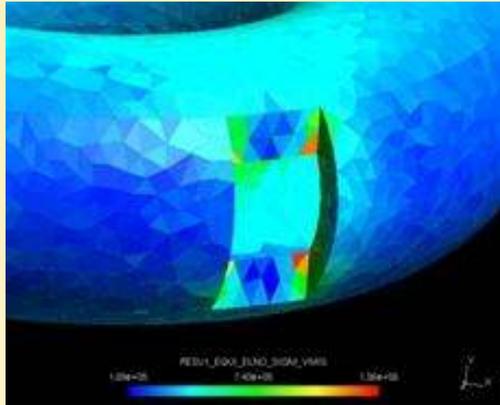


~March 2005 : Simulation of 100 particles with **drifts** for  $10\mu\text{s}$  , and magnetic surfaces. Language : **VB**

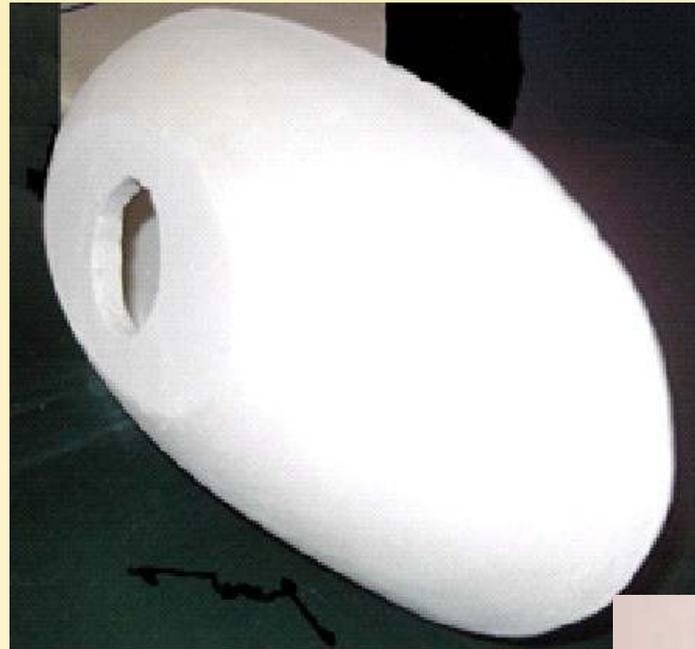


October 2006 ↑ : Simulation of 300 quasi-particles with **drifts, trapped particles and collisions** (only 10 in this graph) for  $150\mu\text{s}$  in 30 PC-minutes. Improved fast guiding centre method. (Top) Helically trapped particle in Boozer-like co. Machine : **UST\_1** . Language : **JAVA**

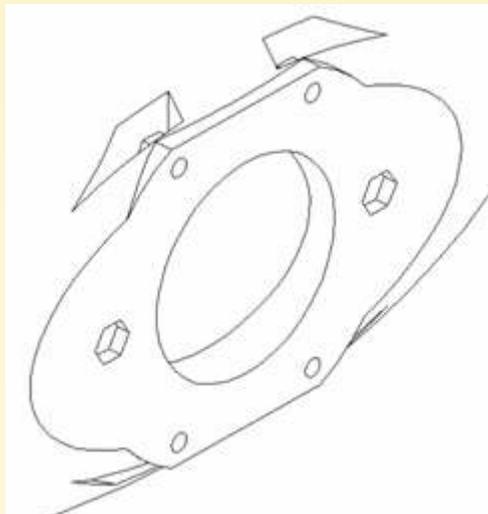
# Development of vacuum vessel



July 2005 Von Misses stress around the port. Calculation using **ASTER-GMSH**. Machine : A rough **UST\_1**



October 2005  
A porcelain piece to test the ideas. Cracks appeared + possible excessive outgassing → Idea abandoned

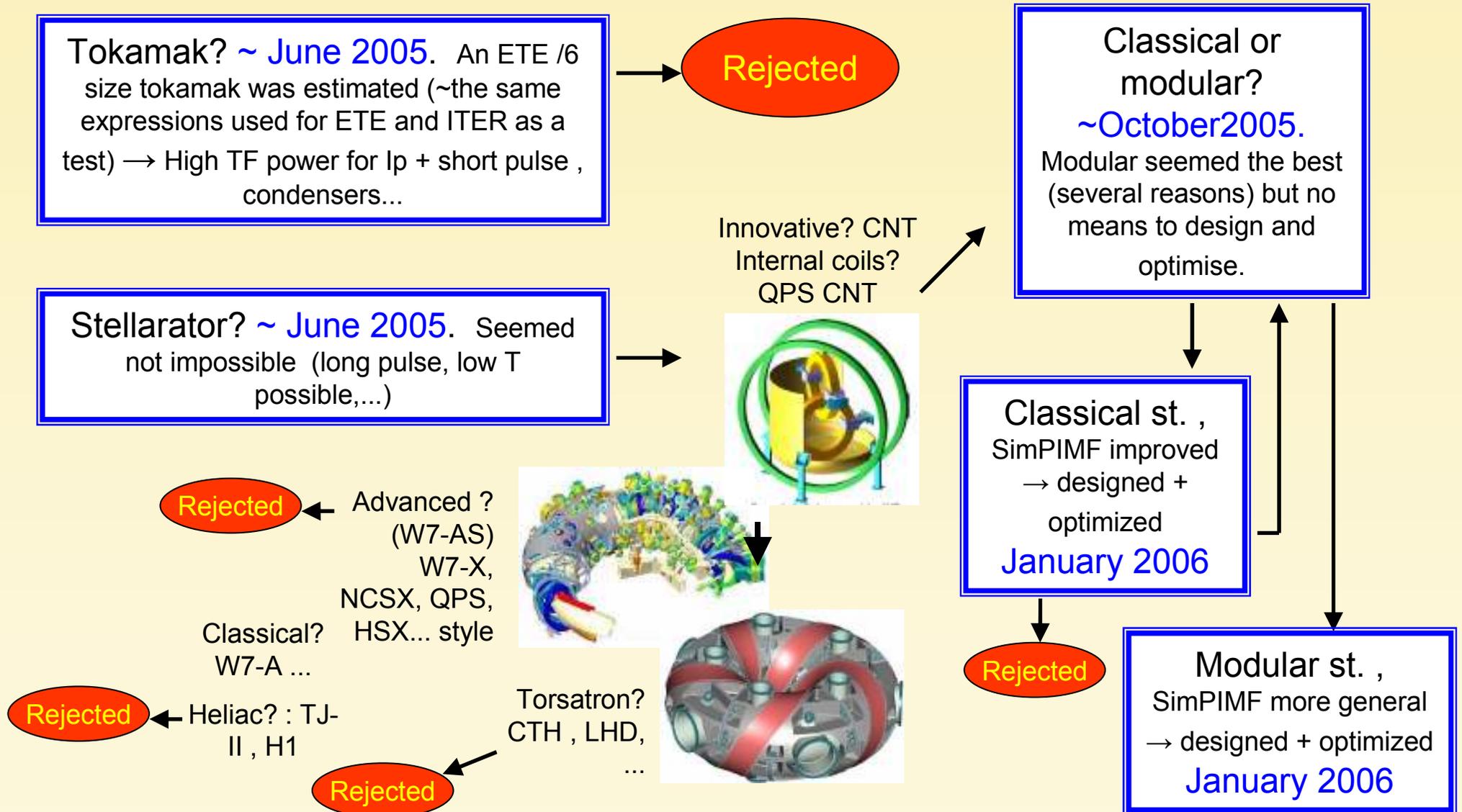


July 2005  
Idea about a non-protuberant port



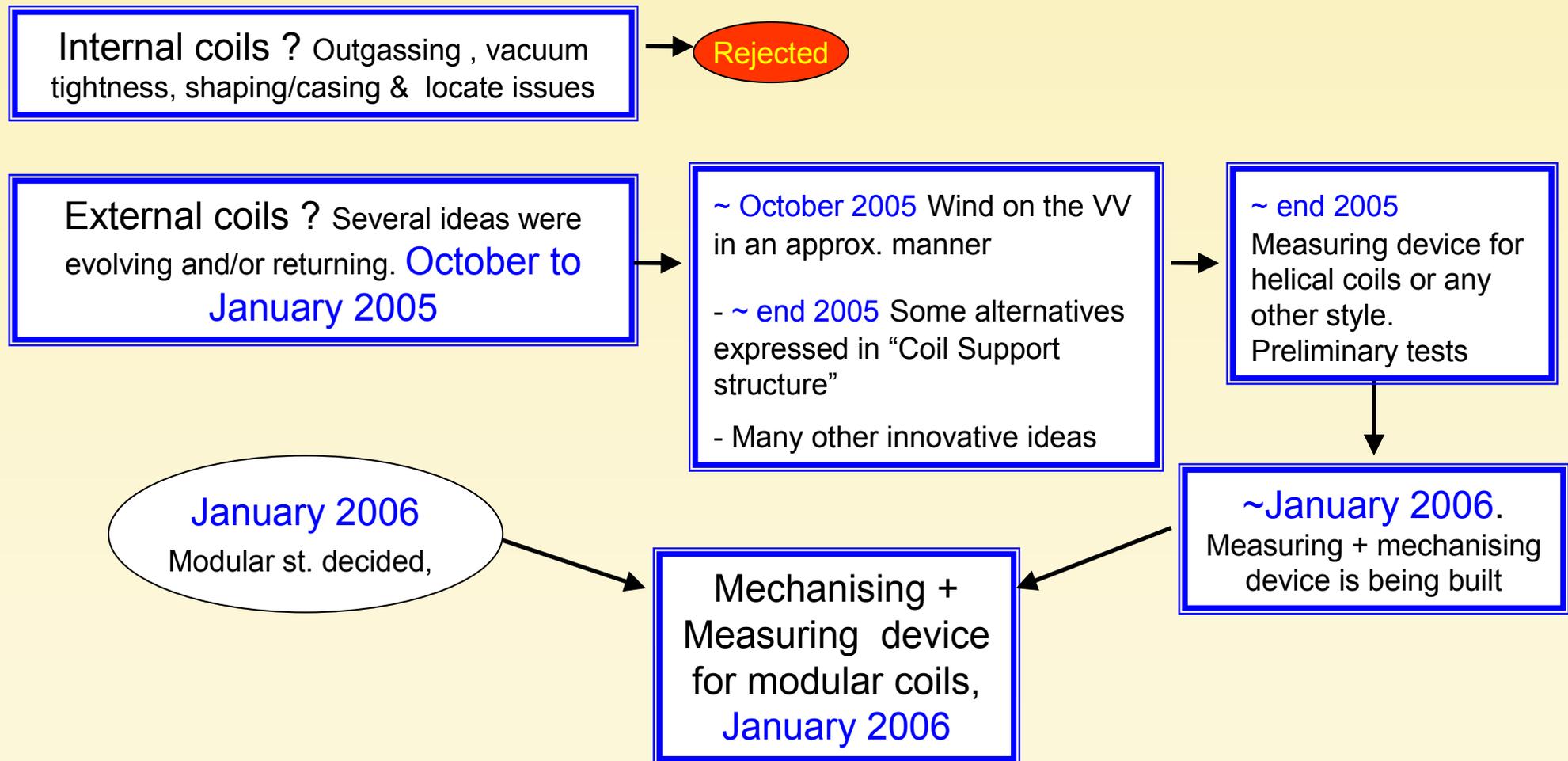
February 2006  
The cooper vacuum vessel is tested (leaks, outgassing..)

# Decision of machine style



# Decision process for coils

- How to produce accurate modular coils at low cost?



# *Present tasks and questions*

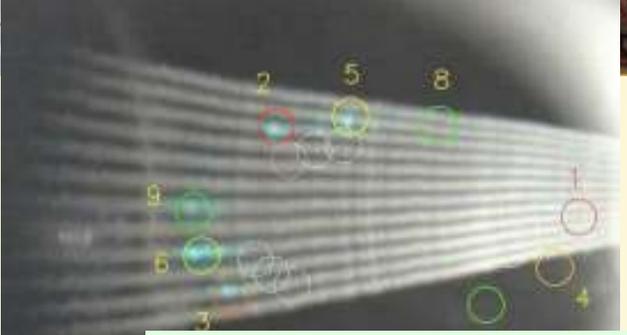
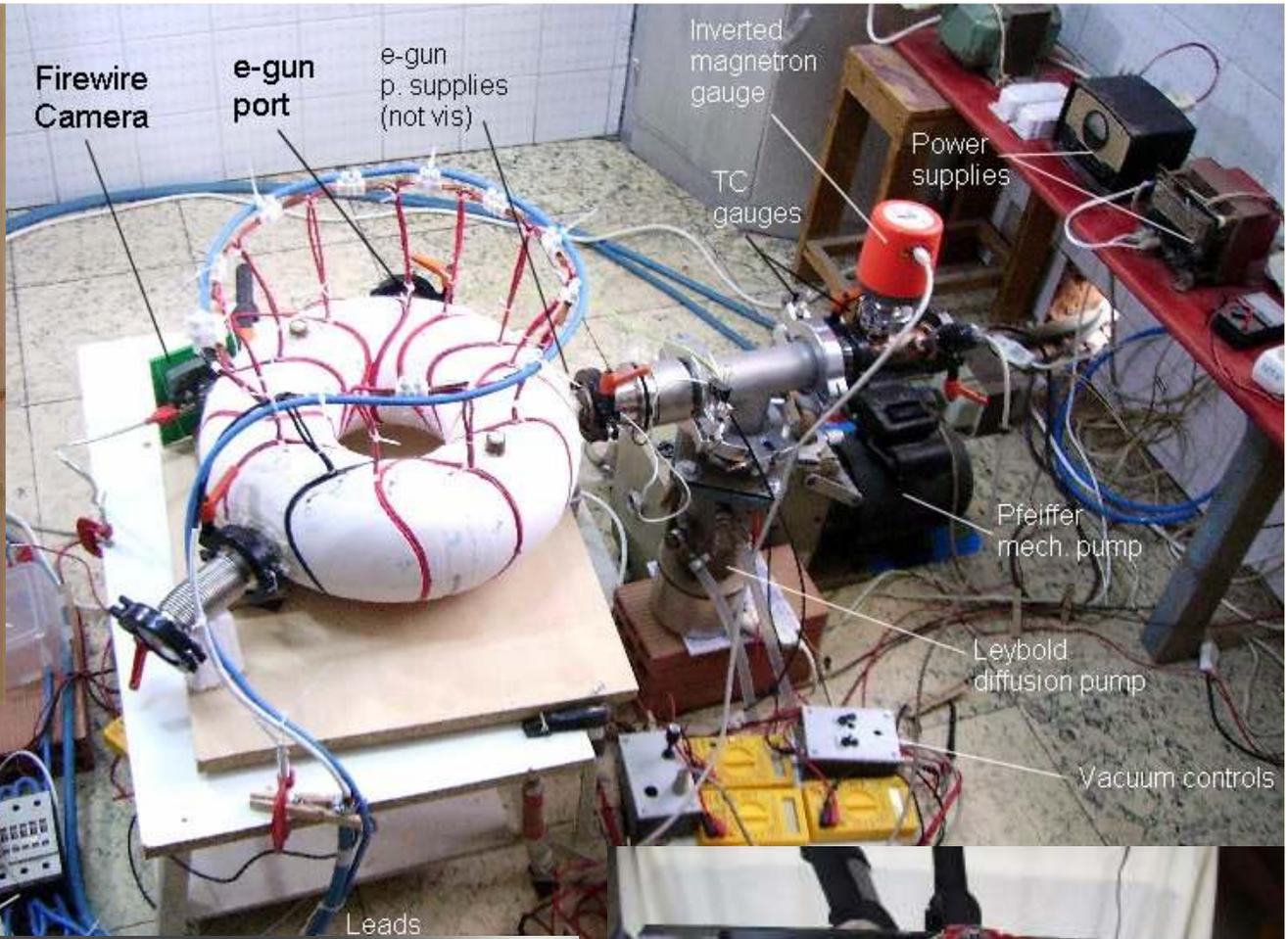
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## Present and future tasks

- Developing the **Heating system for UST\_1** : Some antenna and transmission issues + cost of couplers and waveguides
- Improve **Collisions module** in SimPIMF to better simulate particles in UST\_1 ~ transport.
- **Start-up the RGA system** (AMETEK QUADLINK DYCOR mass spectrometer). Issues: very low cost used instrument without warranty nor manual.
- Is possible to produce accurate real-**3D modular coils**, HSR-3, QPS ... style, at low cost?

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End  
of the UST\_1 project,  
by now.



More information in [www.fusionvic.org](http://www.fusionvic.org)



